

University of Thessaly - Electrical and Computer Engineering
Department

CE664 - Asynchronous Circuit Design

Fall Term - Academic Year 2015-2016

3rd Assignment

26/11/2015 to 18/12/2015

C. P. Sotiriou

3rd Assignment's Goal

Each assignment is composed of one or more tasks, which require thought, design, programming or a combination of all. The goal of the 3rd assignment is practice with Hazard and Timing Model Analysis, PTnet transformations, and circuit implementation using the Petrify tool.

Task 1 (Timing Model and Hazard Analysis)

Figure 1 illustrates two control circuits which implement a simple FSM-based counter. Figure 1(a) is a gray-code encoded 2-level implementation, whereas 1(b) is a corresponding One-Hot version.

Perform Sequential Hazard analysis on circuit 1(a) for initial state $Y_1Y_0 = 00$, initial value of input $x = 0$, and $0 \rightarrow 1$ transition on x , using both (i) ternary and (ii) 13-level logic. Comment on the differences observed between the two different analysis logics (pros and cons), and the type of manifested Hazards for the given input transition and initial state.

Now, perform the same two analyses to circuit 1(b), but also verifying its timing model. Based on your analysis results, establish whether the Timing Model of circuit 1(b) is SI, Fundamental Mode or Timed (requires specific timing assumptions for correct operation)? Clearly explain why.

Task 2 (PTnet Analysis using SM-Covering)

In the lecture notes, the Toggle element is presented, which consists of a single input and two outputs, and its function is to steer events alternatively to each output. The PTnet

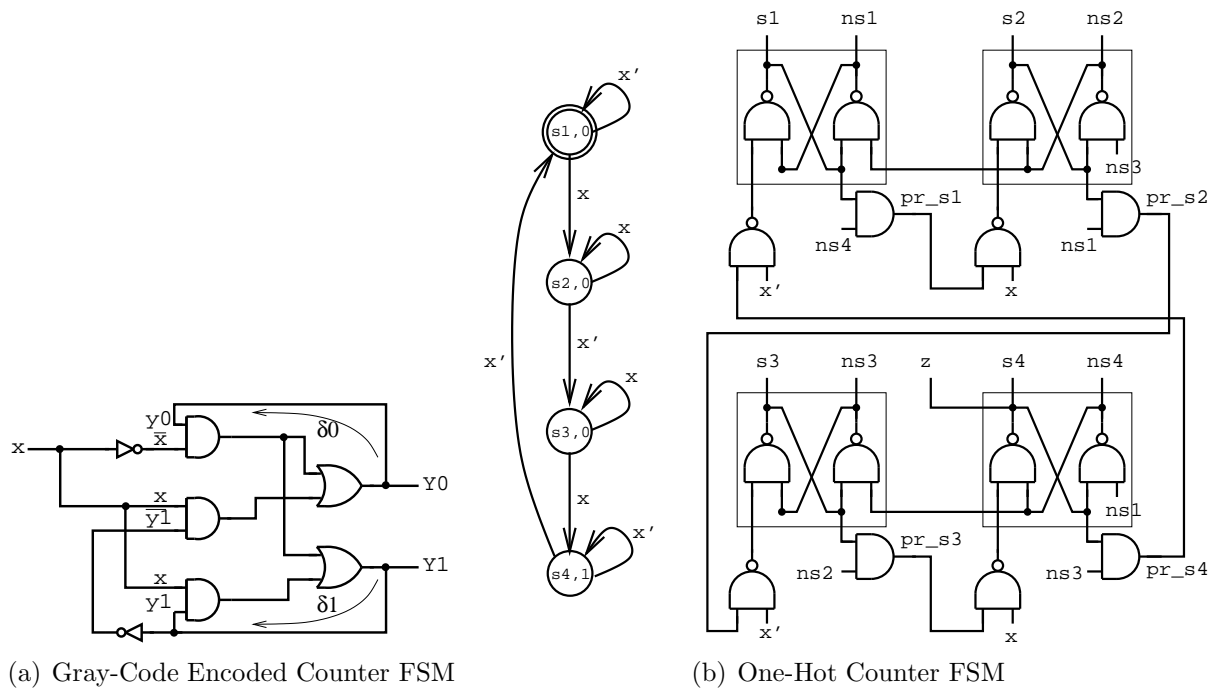


Figure 1: Circuits for Operation Model and Hazard Analysis

specification of Toggle is also detailed in the lecture notes.

Your task is to find an SM-Cover for the Toggle PTnet. This can be accomplished by computing a set of minimal Deadlocks (which must also be traps and obviously valid S-Components), that collectively cover all of the original PTnet's places.

To compute the minimal Deadlocks use Esparsa's/Kepmper's Algorithm `Get_Minimal_Deadlock()` repeatedly on uncovered places of the net. Illustrate the resultant SM-Cover, along with a trace of the algorithmic execution for the order of places you specified.

Task 3 (Petrify Tutorial Examples)

In Chapter 3 of the Petrify tutorial you will find the **xyz** STG example, with the minor difference that **x** is defined as an input, whereas **y** and **z** are outputs. By following the tutorial instructions implement the **xyz** using (a) Complex gates and (b) Generalised C-Elements. Generate and illustrate the State Graph, as well as present the two resultant circuit implementations in schematic form.

Now implement the **abc** example, of Chapter 4 of the Petrify tutorial. Clearly explain, why the state encoding problem is not solvable, with reference to possible signal paths in the relevant State Graph. Explain clearly (a) what causal environment behaviour which can guarantee that the circuit is SI, and (b) what timing assumption you can introduce

to resolve the state encoding conflicts and what of what delay model type this circuit will then be.

Task 4 (STG Circuit Implementation using Petrify)

For this task, you are required to derive a circuit implementation, using Petrify, for the 4-phase to 2-phase handshake converter. A PTnet specification for this circuit can be found in the lecture notes.

Firstly, describe the original 4-phase to 2-phase handshake converter PTnet in a Petrify .g file. Note that the aforementioned PTnet includes two Asymmetric Choice (AC) places. Check whether Petrify is able to derive a State Graph or implement this specification.

Next, you will have to convert the original PTnet into one without AC places, *i.e.* into an STG. This may be performed by instantiating the same signal multiple times, and considering the unfolded behaviour of the original PTnet. Describe the derived STG for the 4-phase to 2-phase handshake converter PTnet in a Petrify .g file and (a) derive its State Graph and (b) a Complex Gate implementation, presenting it in schematic form.

Deadline and Submission

The deadline for the 1st Assignment Set is **18/12/2015**. You should submit your solution set, before the deadline, via the **e-Class** portal.