

ΗΥ416 ΓΡΑΦΙΚΑ ΥΠΟΛΟΓΙΣΤΩΝ

Αποκοπή

Π. ΤΣΟΜΠΑΝΟΠΟΥΛΟΥ

ΠΑΝΕΠΙΣΤΗΜΙΟ ΘΕΣΣΑΛΙΑΣ

ΤΜΗΜΑ ΗΛΕΚΤΡΟΛΟΓΩΝ ΜΗΧΑΝΙΚΩΝ & ΜΗΧΑΝΙΚΩΝ ΥΠΟΛΟΓΙΣΤΩΝ

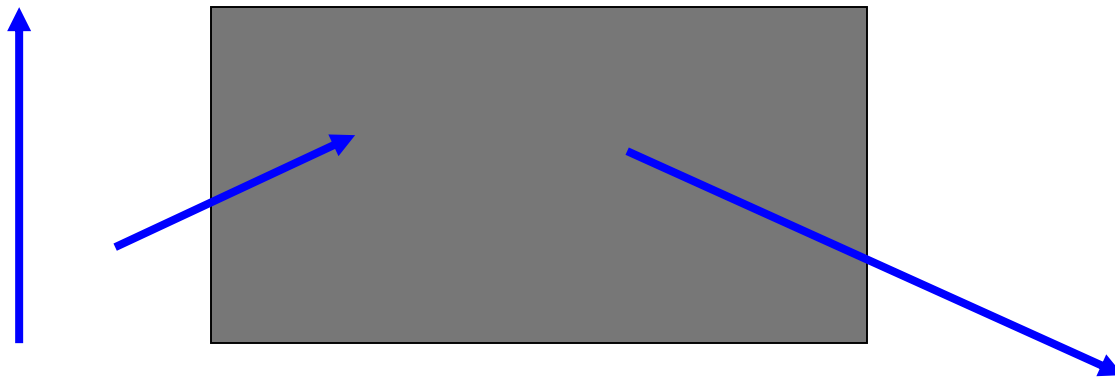
Liang-Barsky Algorithm

Liang-Barsky Algorithm

- ▶ Cyrus-Beck Algorithm, earlier approach
- ▶ Liang - Barsky Algorithm, later-better-independent approach
- ▶ Parametric definition of a line:
 - ▶ $x = x_1 + u\Delta x$
 - ▶ $y = y_1 + u\Delta y$
 - ▶ $\Delta x = (x_2 - x_1), \Delta y = (y_2 - y_1), 0 \leq u \leq 1$
- ▶ Lines are oriented: classify lines as moving inside to out or outside to in
- ▶ Goal: find range of u for which x and y both inside the viewing window

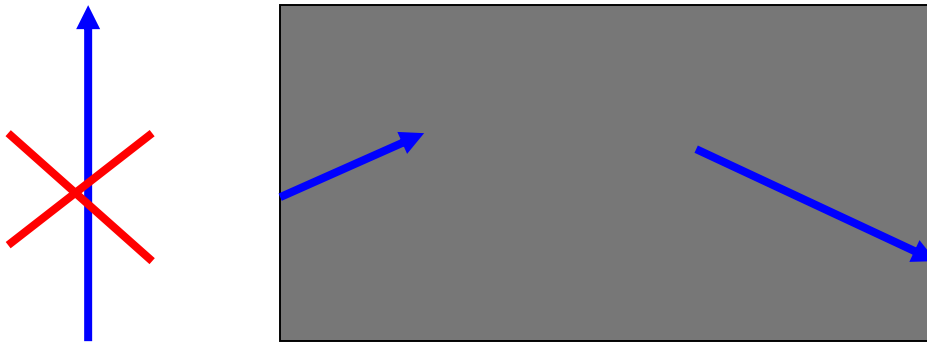
Liang-Barsky Algorithm

- ▶ For lines starting outside of boundary, update its starting point (u_1)
- ▶ For lines starting inside of boundary, update end point (u_2)
- ▶ For lines paralleling the boundaries and outside window, reject it.



Liang-Barsky Algorithm

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Liang-Barsky Algorithm

- ▶ Mathematically:

- ▶ $x_{\min} \leq x_1 + u\Delta x \leq x_{\max}$

- ▶ $y_{\min} \leq y_1 + u\Delta y \leq y_{\max}$

- ▶ Rearranged

- ▶ 1: $u^*(-\Delta x) \leq (x_1 - x_{\min})$

- ▶ 2: $u^*(\Delta x) \leq (x_{\max} - x_1)$

- ▶ 3: $u^*(-\Delta y) \leq (y_1 - y_{\min})$

- ▶ 4: $u^*(\Delta y) \leq (y_{\max} - y_1)$

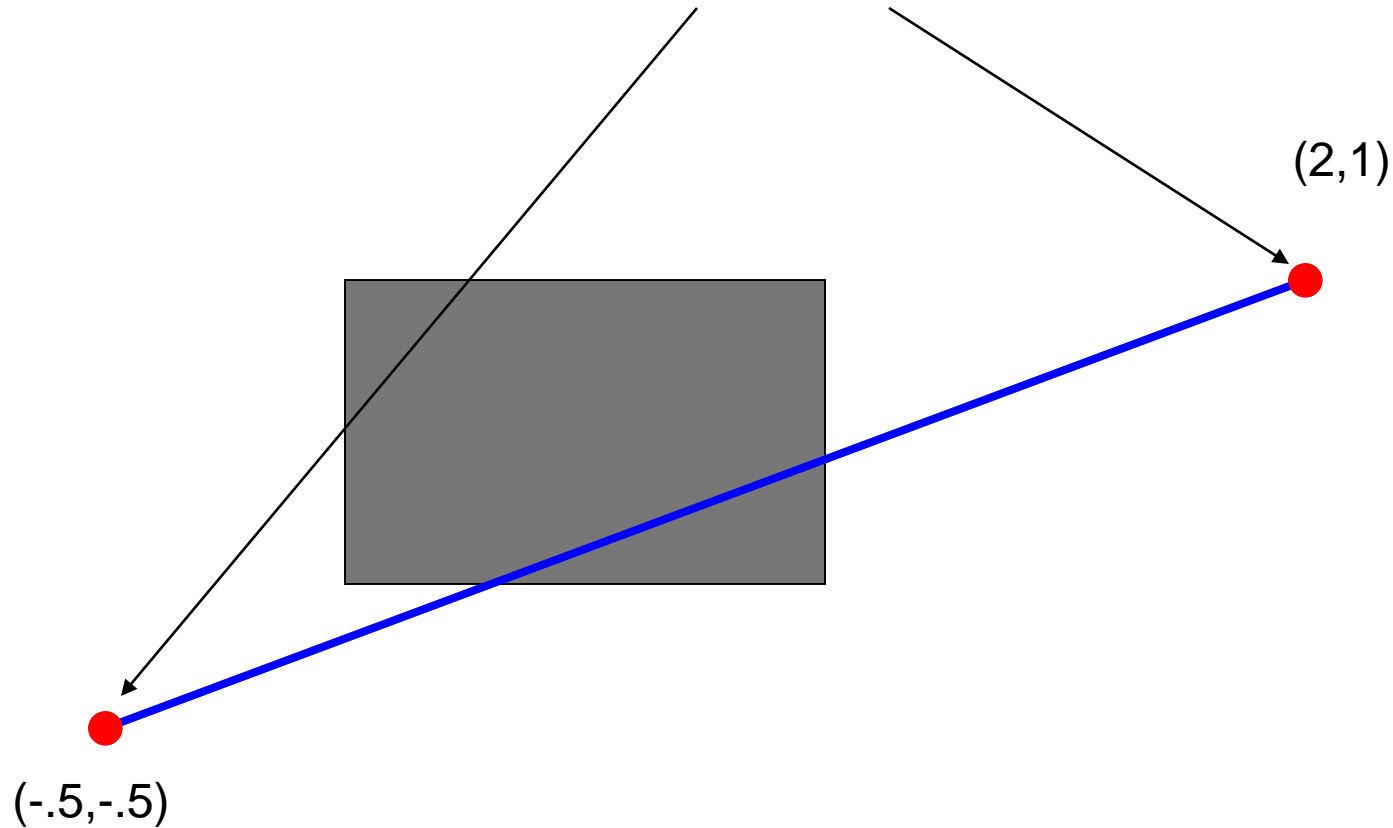
- ▶ gen: $u^*(p_k) \leq (q_k), k=1,2,3,4$

Liang-Barsky Algorithm

- ▶ Initial values: $u_1 = 0, u_2 = 1$
- ▶ Rules:
 1. $p_k = 0$: the line is parallel to boundaries
 - ▶ If for that same $k, q_k < 0$, it's outside
 - ▶ Otherwise it's inside
 2. $p_k < 0$: the line starts outside this boundary
 - ▶ $r_k = q_k / p_k$
 - ▶ $u_1 = \max(0, r_k, u_1)$ /**update starting point**/
 3. $p_k > 0$: the line starts inside the boundary
 - ▶ $r_k = q_k / p_k$
 - ▶ $u_2 = \min(1, r_k, u_2)$ /** update end point**/
 4. If $u_1 > u_2$, the line is completely outside

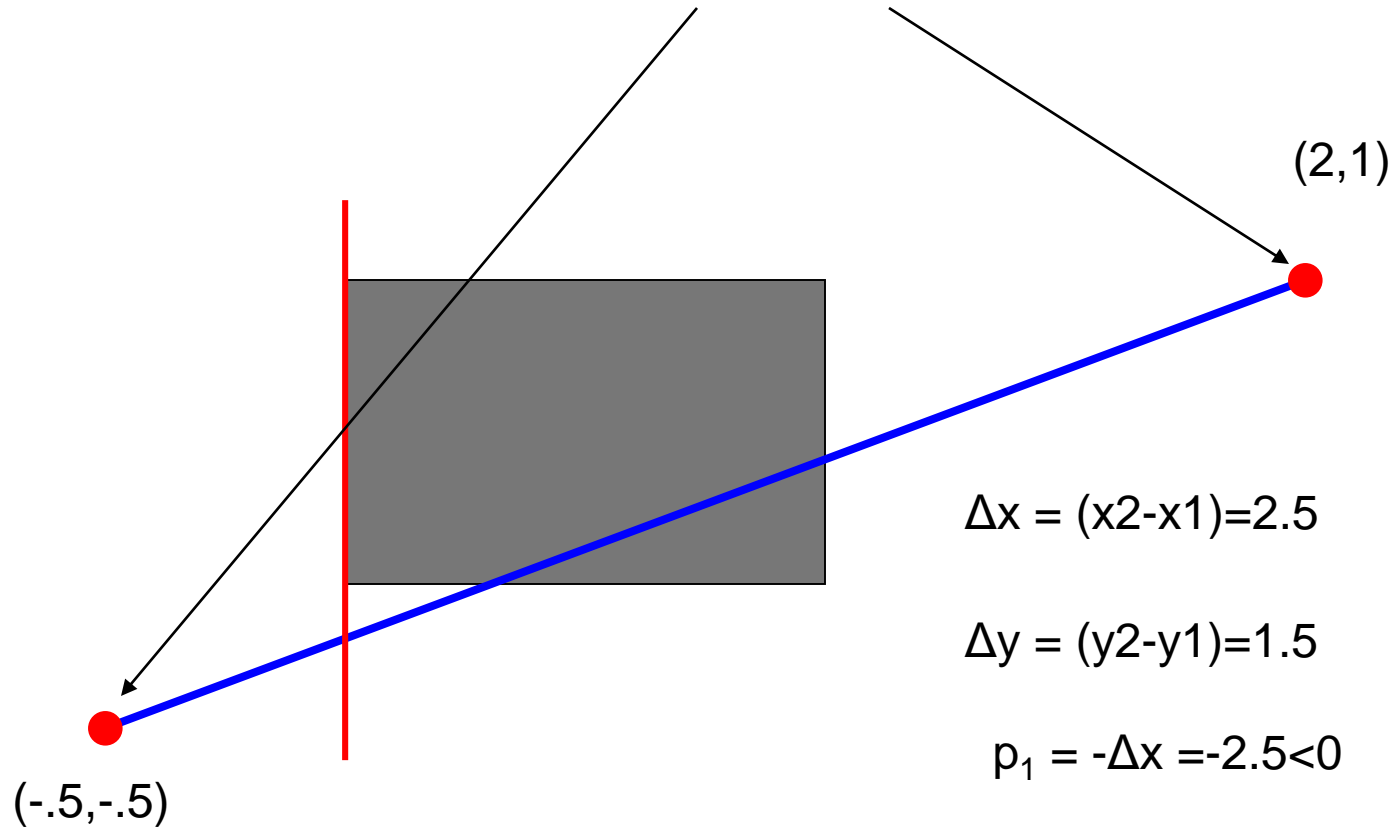
Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0, u_2=1$)



Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0, u_2=1$)



$$\Delta x = (x_2 - x_1) = 2.5$$

$$\Delta y = (y_2 - y_1) = 1.5$$

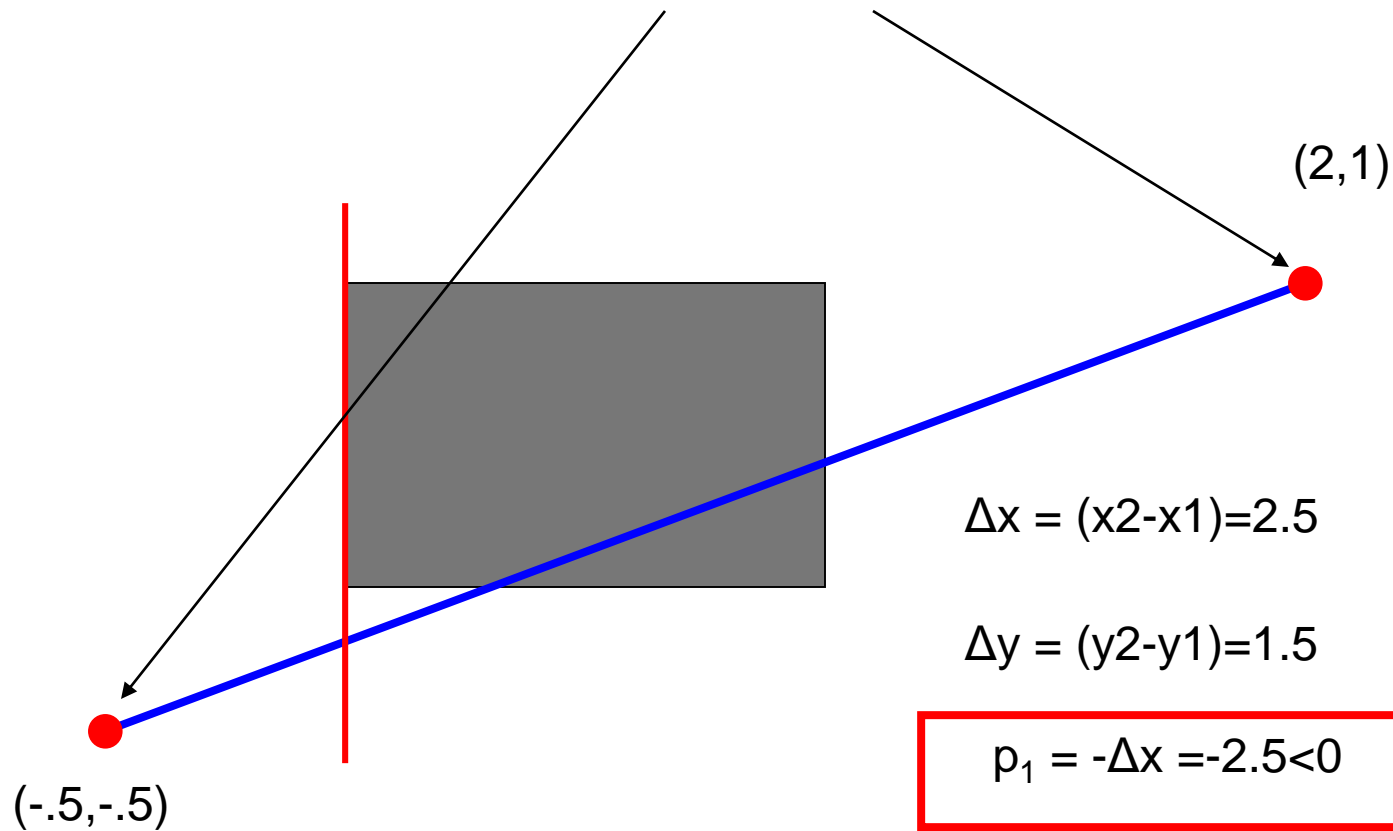
$$p_1 = -\Delta x = -2.5 < 0$$

$$q_1 = (x_1 - x_{\min}) = -0.5$$

$$r_1 = q_1 / p_1 = 0.2$$

Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0, u_2=1$)



line starts outside this boundary

$$\Delta x = (x_2 - x_1) = 2.5$$

$$\Delta y = (y_2 - y_1) = 1.5$$

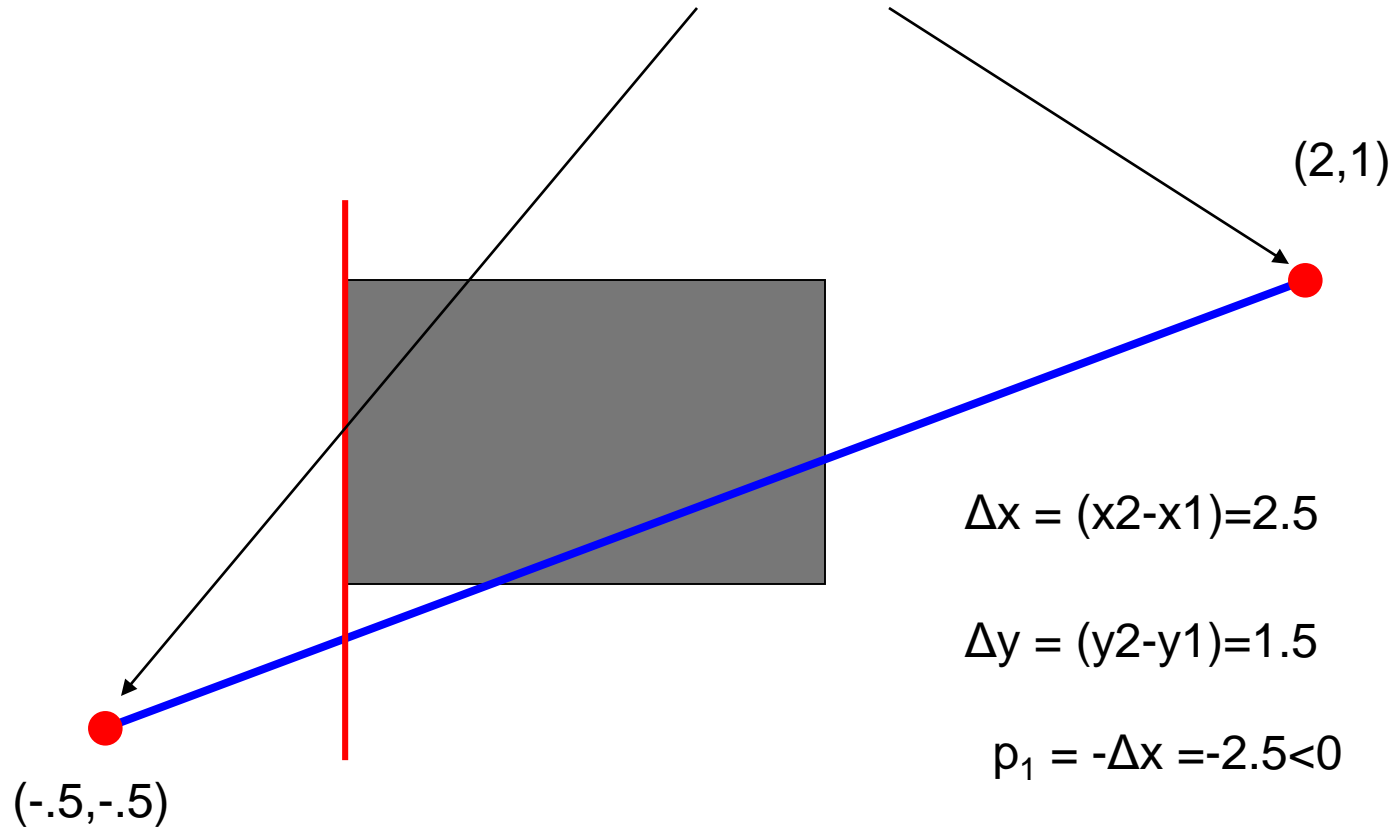
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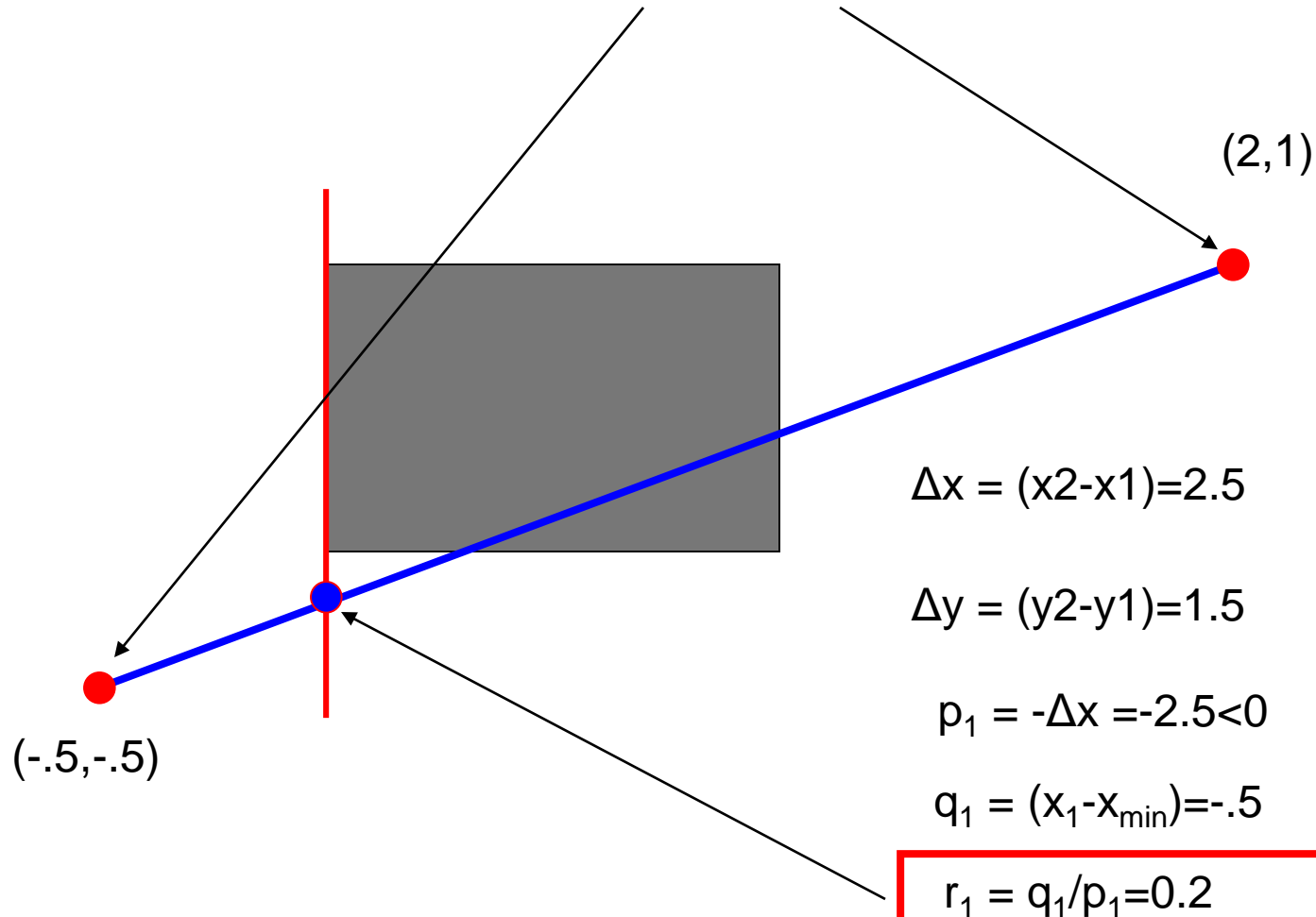
$$p_1 = -\Delta x = -2.5 < 0$$

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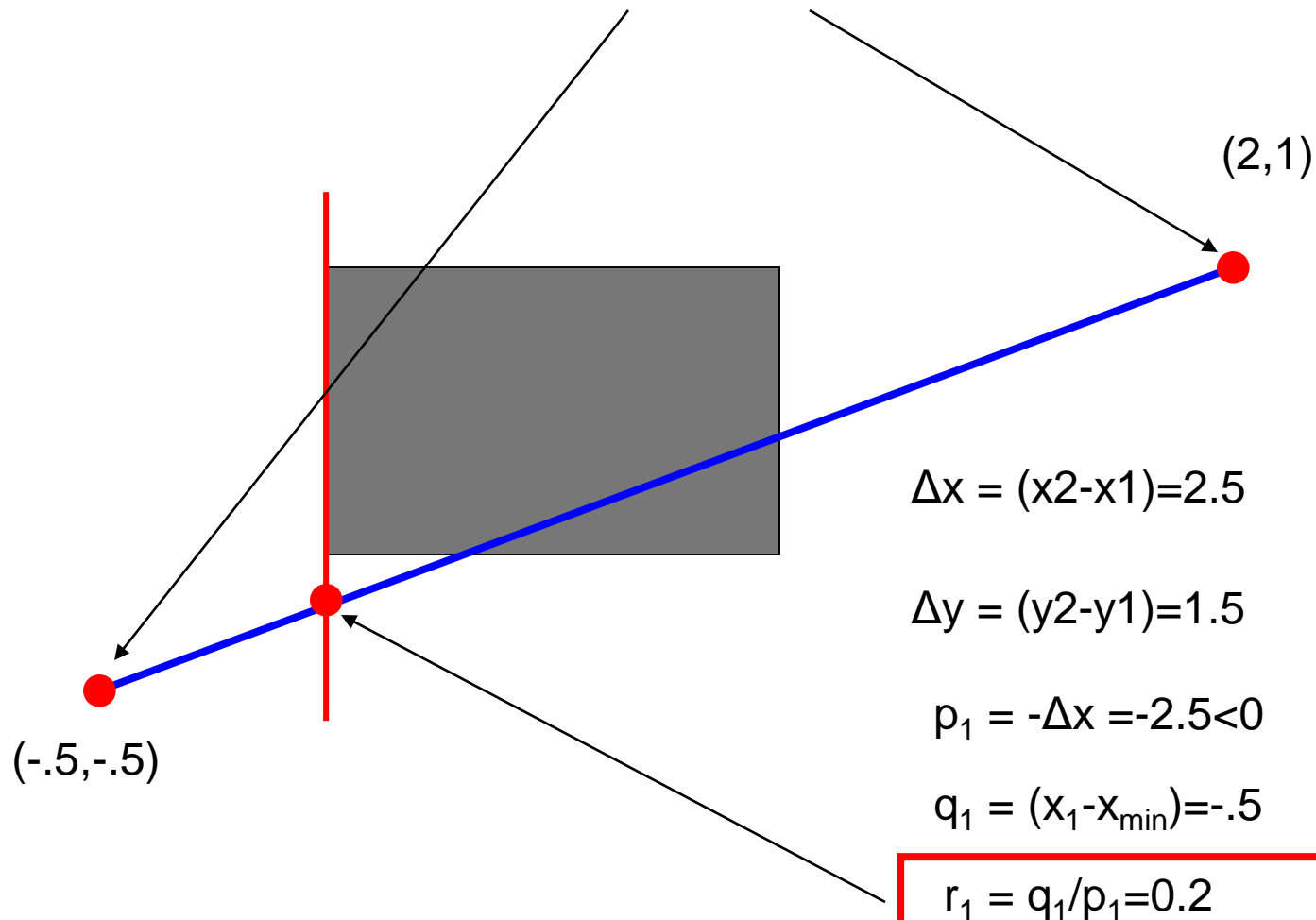
Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0, u_2=1$)



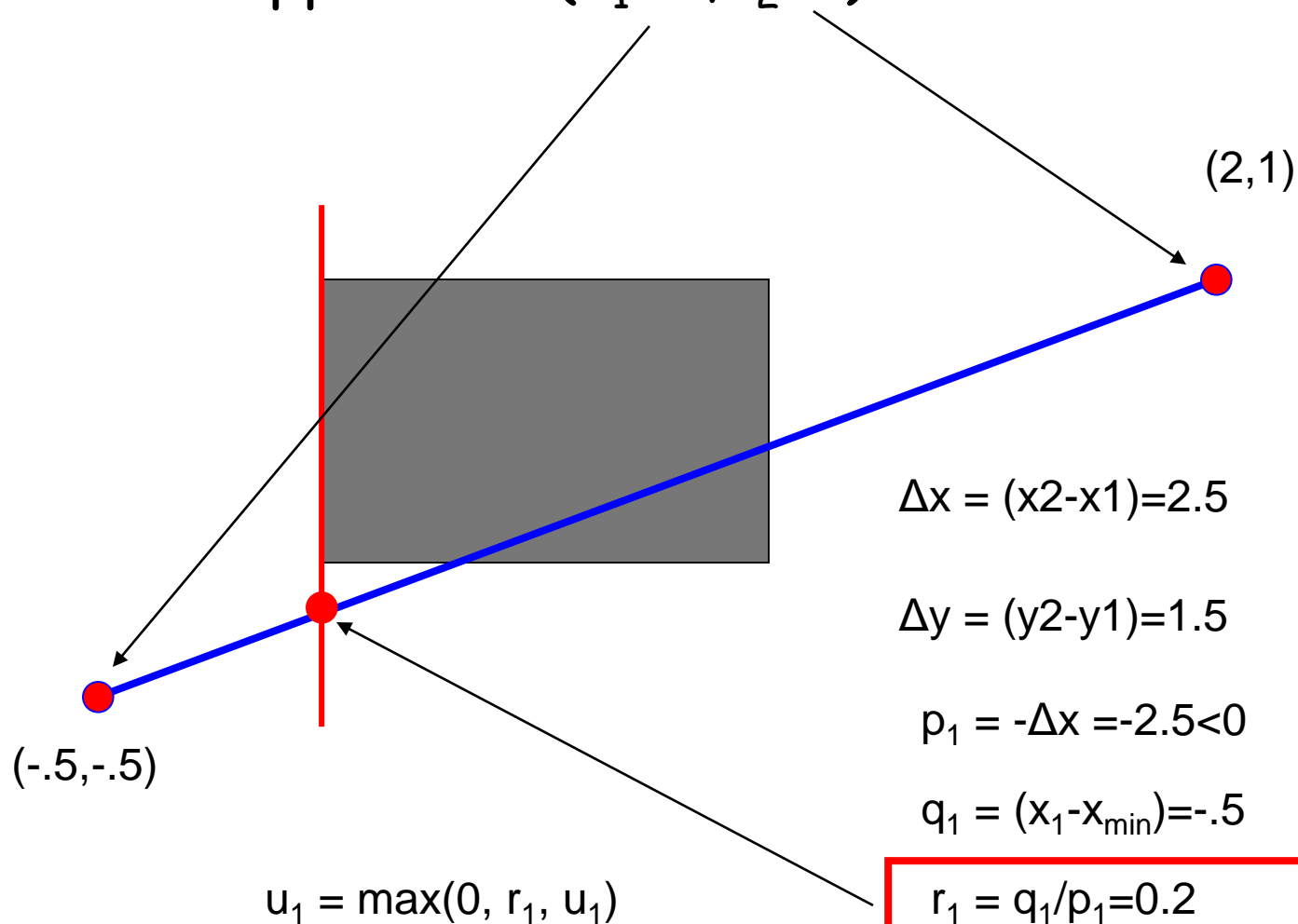
Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0, u_2=1$)



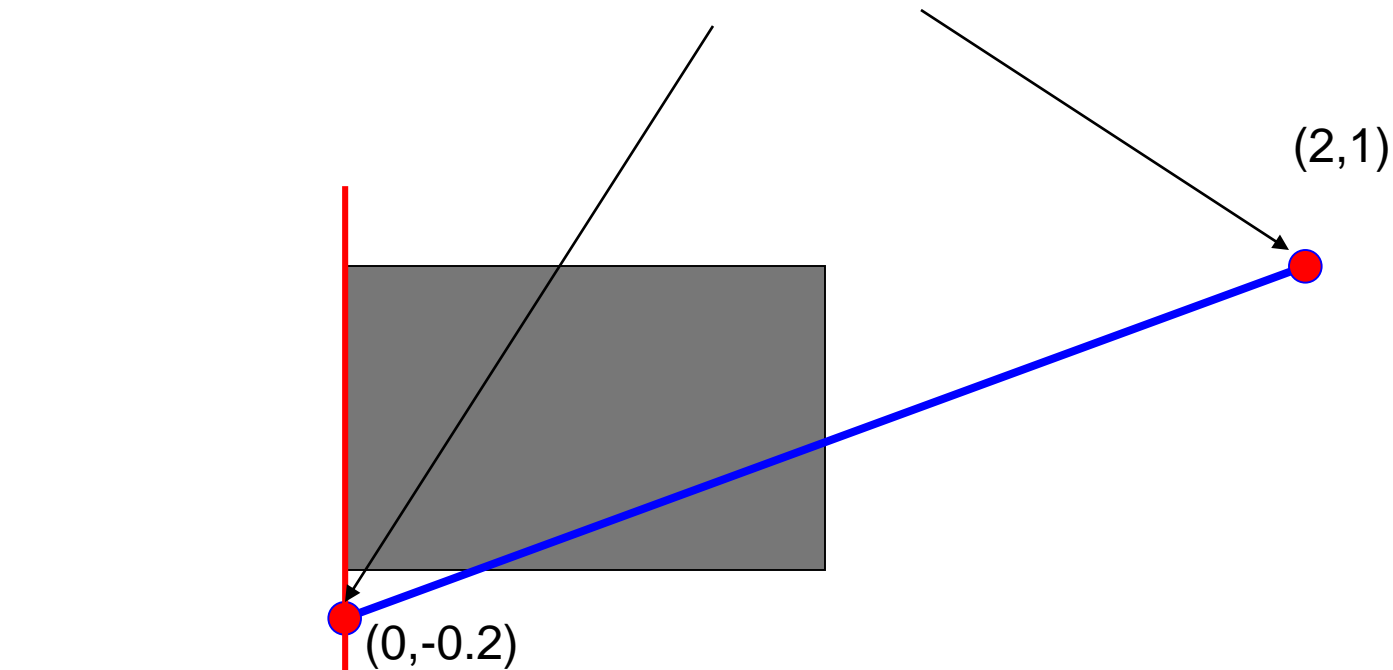
Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0, u_2=1$)



Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0.2, u_2=1$)



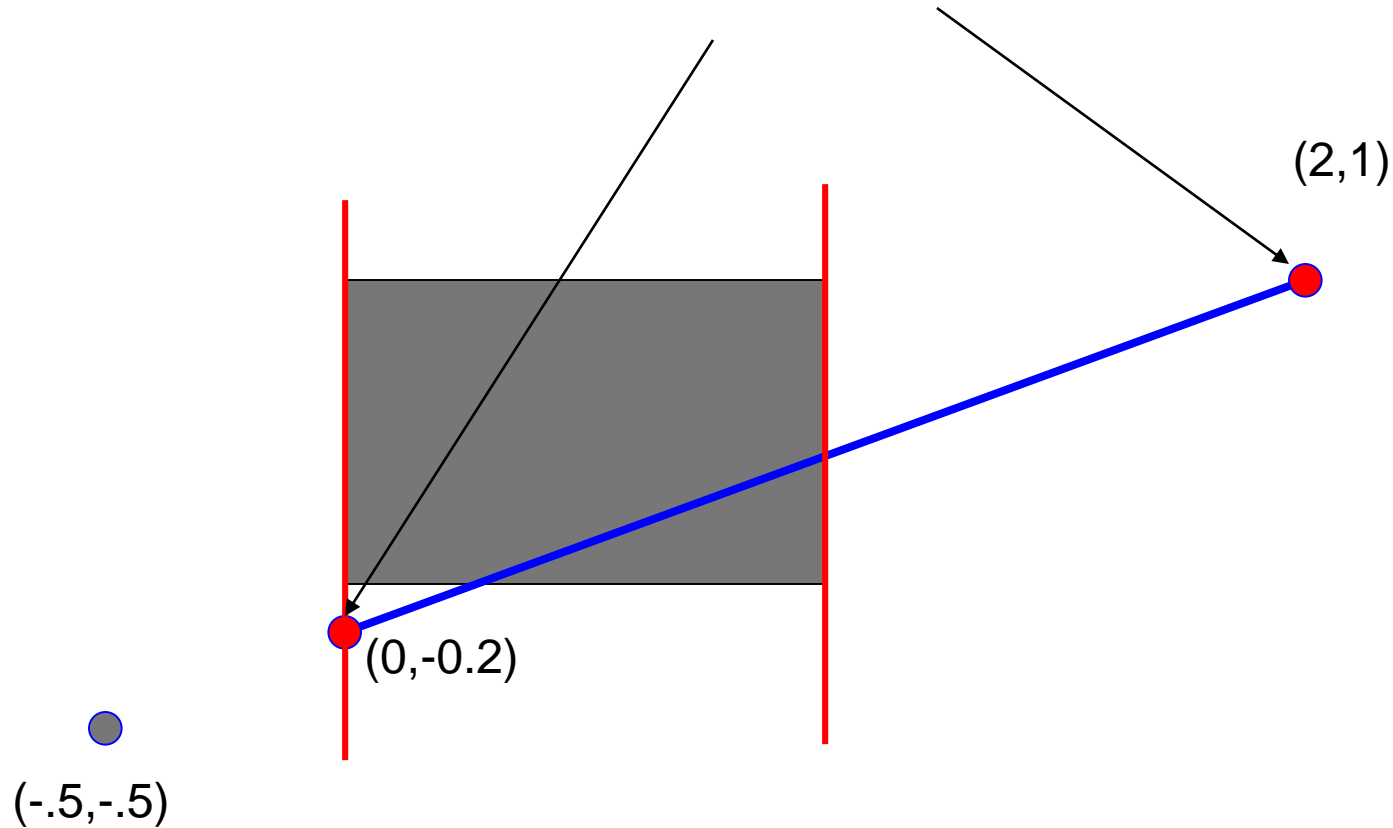
$u_1 < u_2$?

- yes: continue

- no: the line is completely outside window

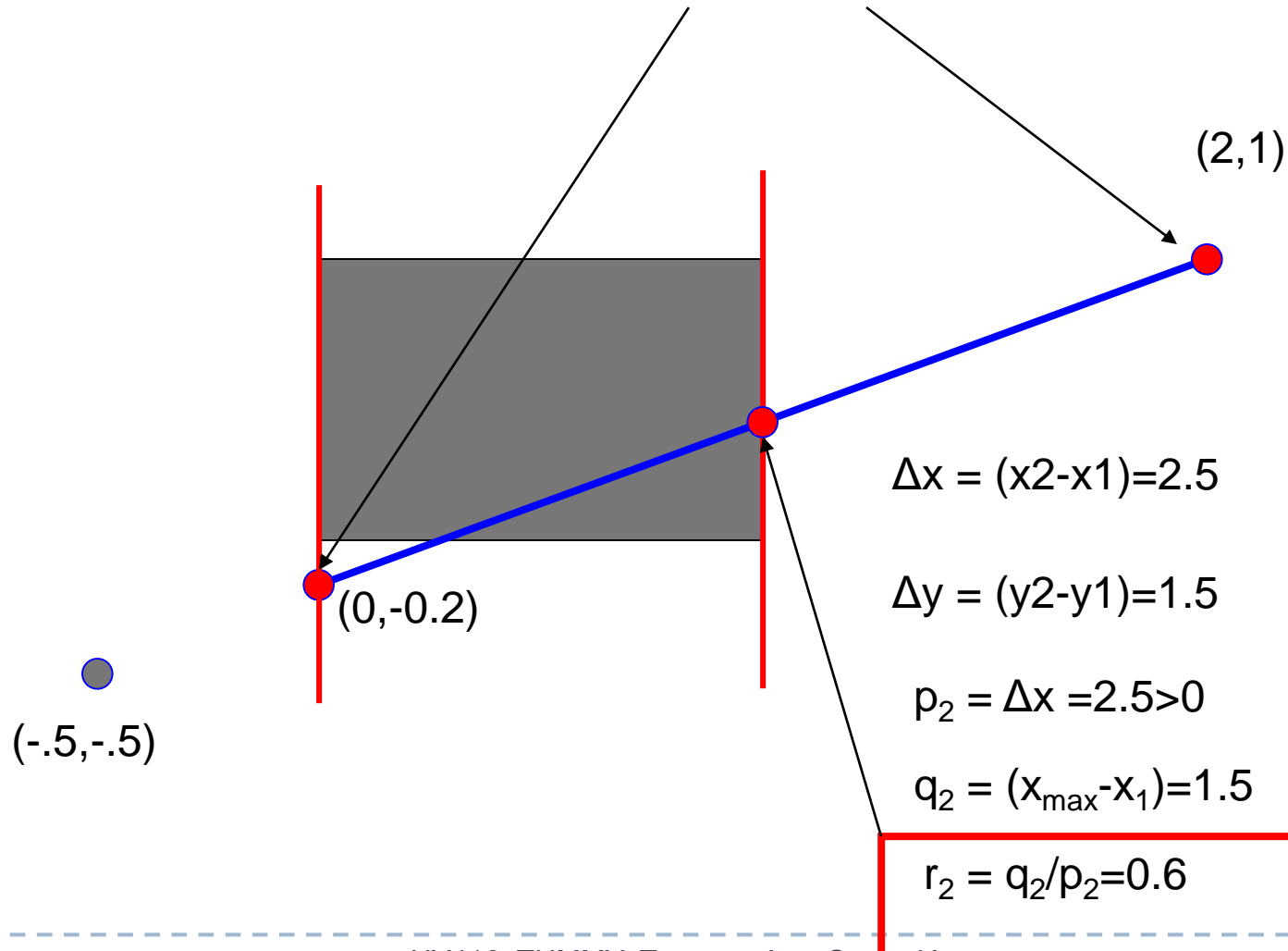
Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0.2, u_2=1$)



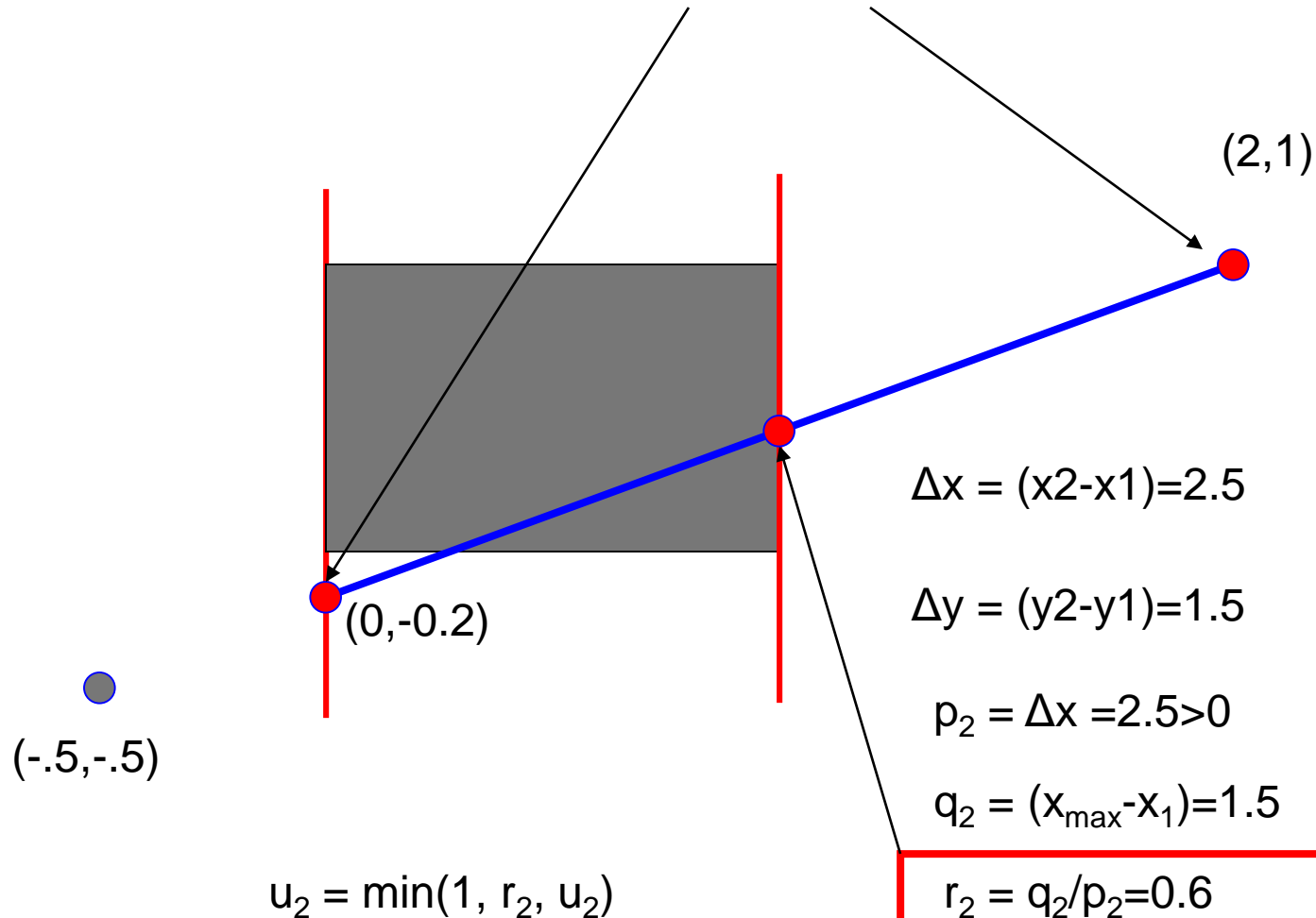
Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0.2, u_2=1$)



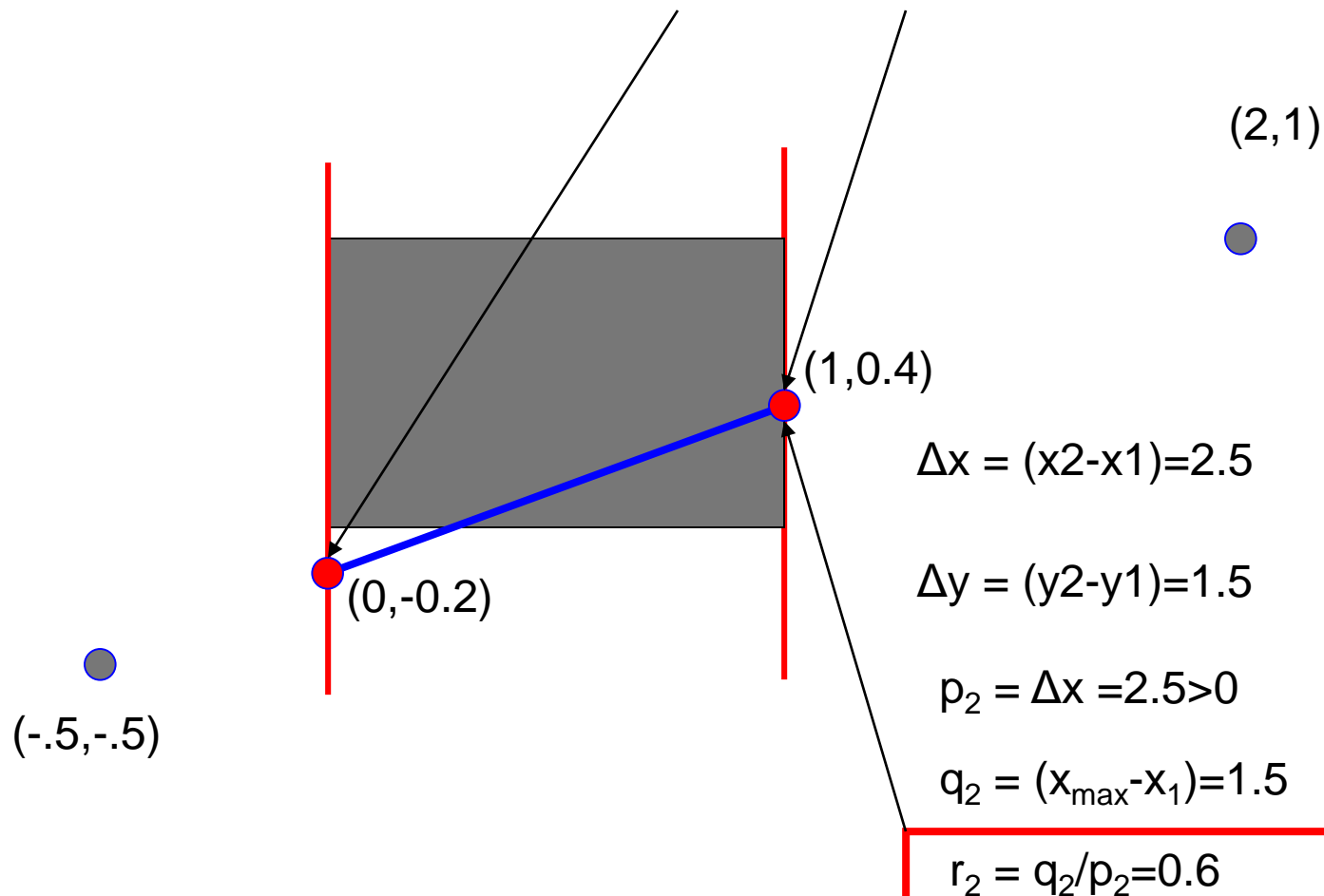
Liang-Barsky Algorithm

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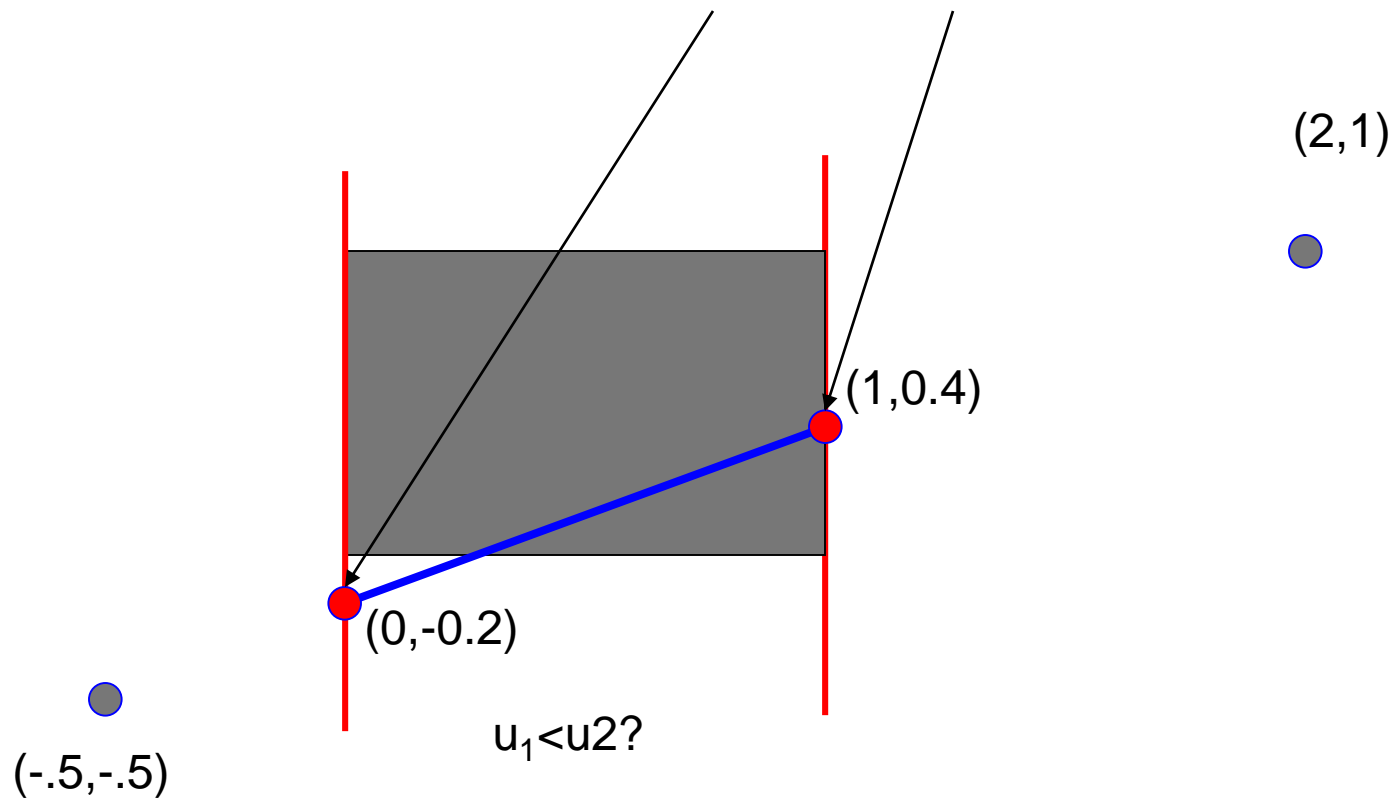
Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0.2, u_2=0.6$)



Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0.2, u_2=0.6$)



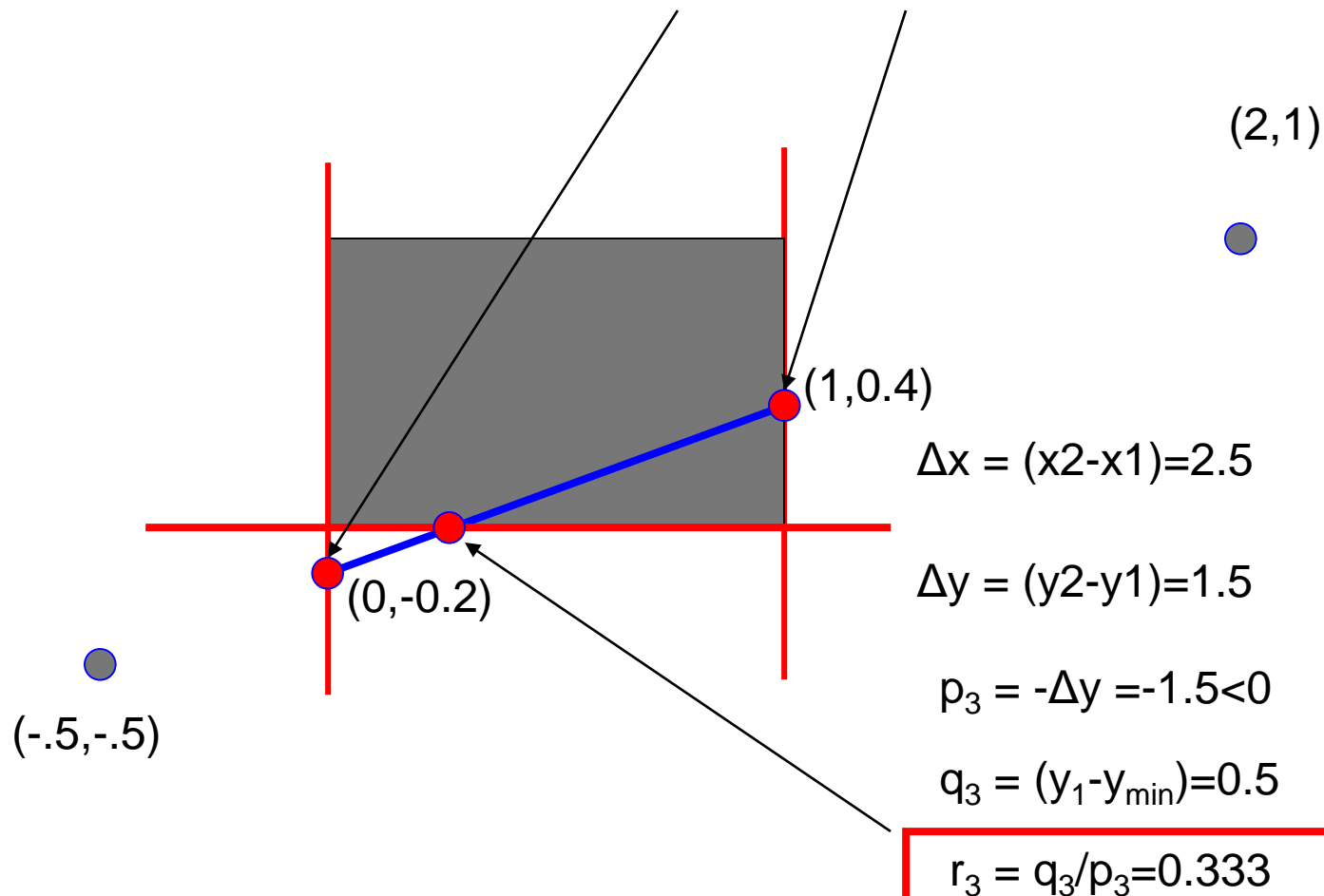
$u_1 < u_2$?

- yes: continue

- no: the line is completely outside window

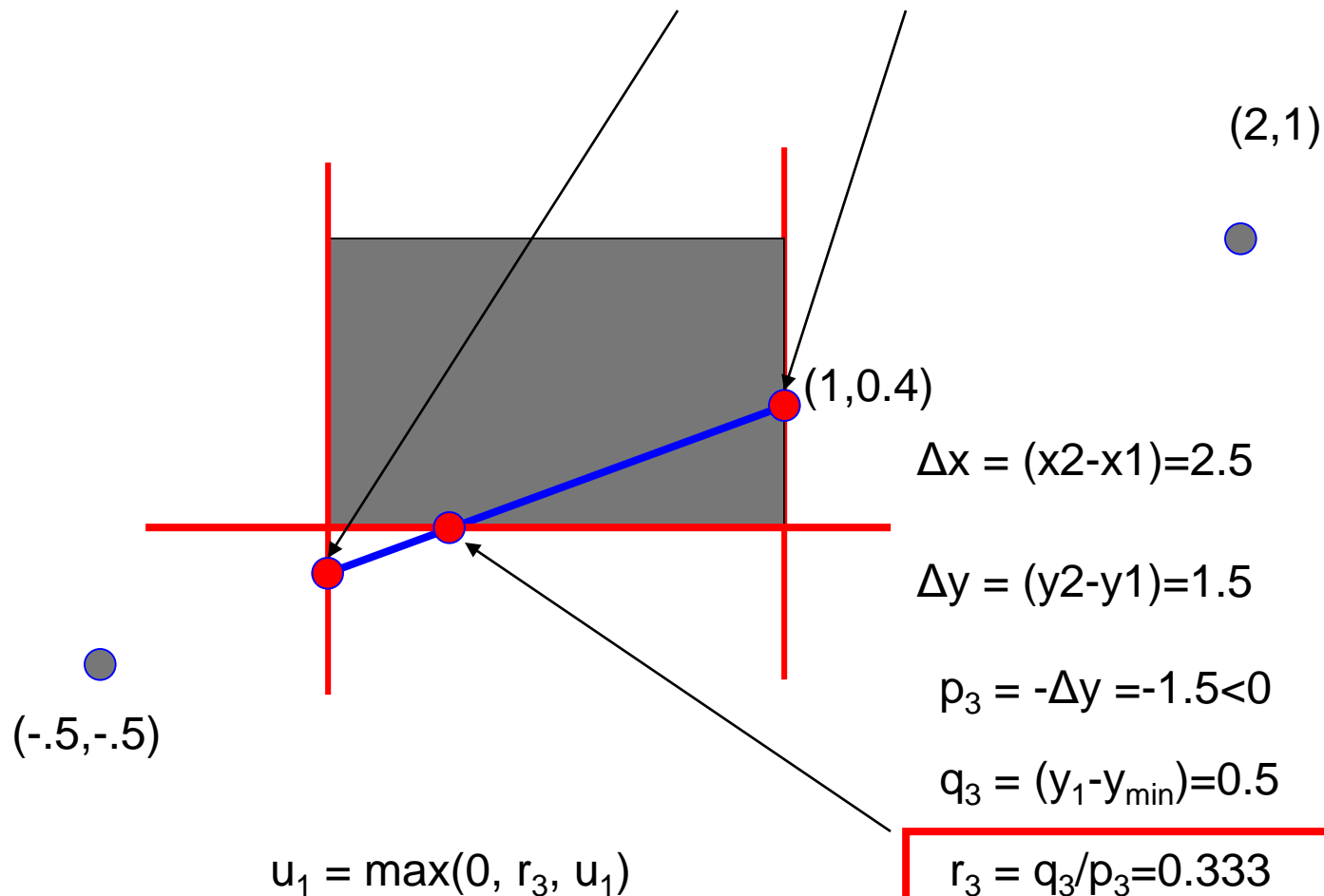
Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0.2, u_2=0.6$)



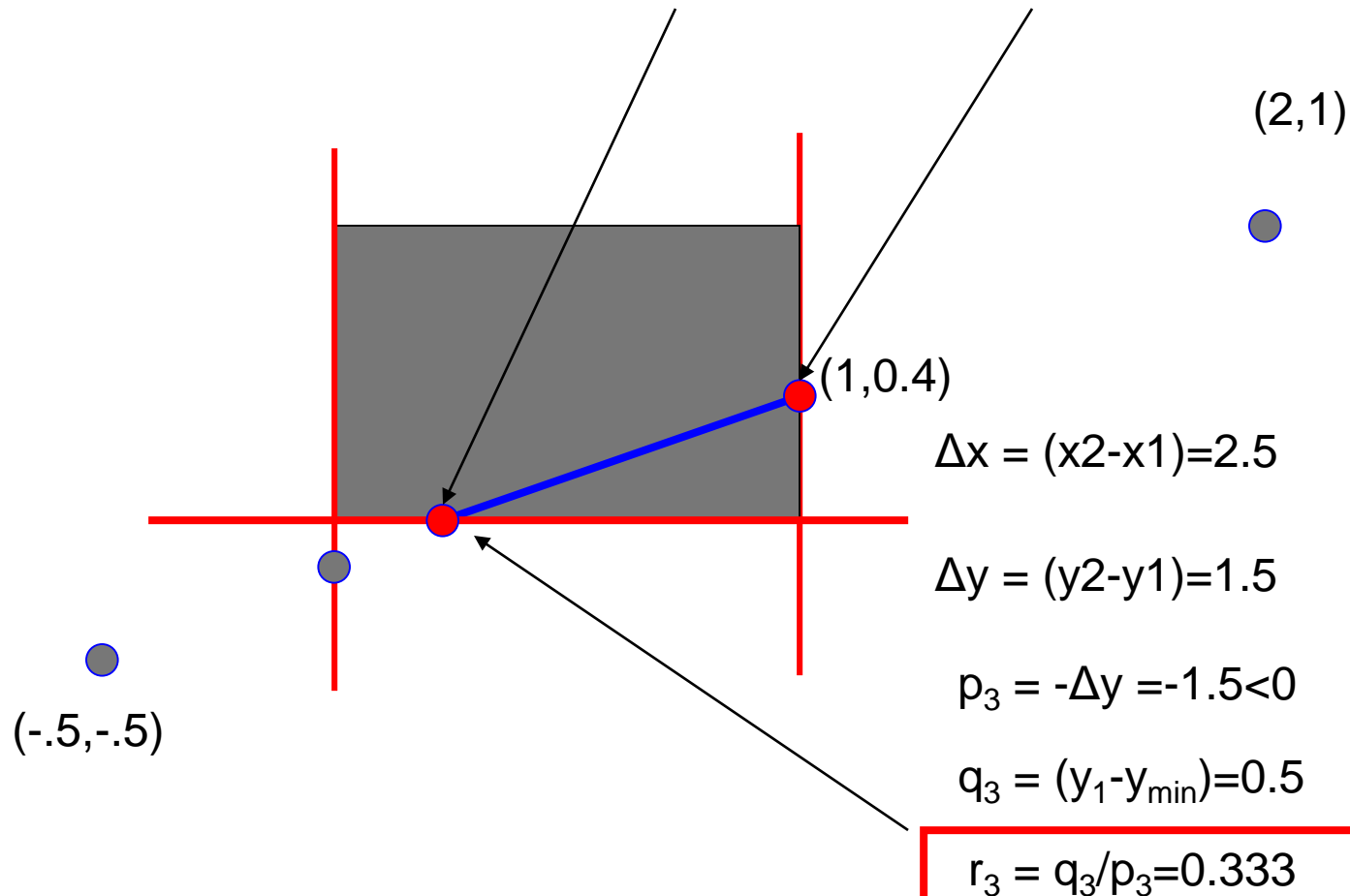
Liang-Barsky Algorithm

- Current clipped line ($u_1=0.2, u_2=0.6$)



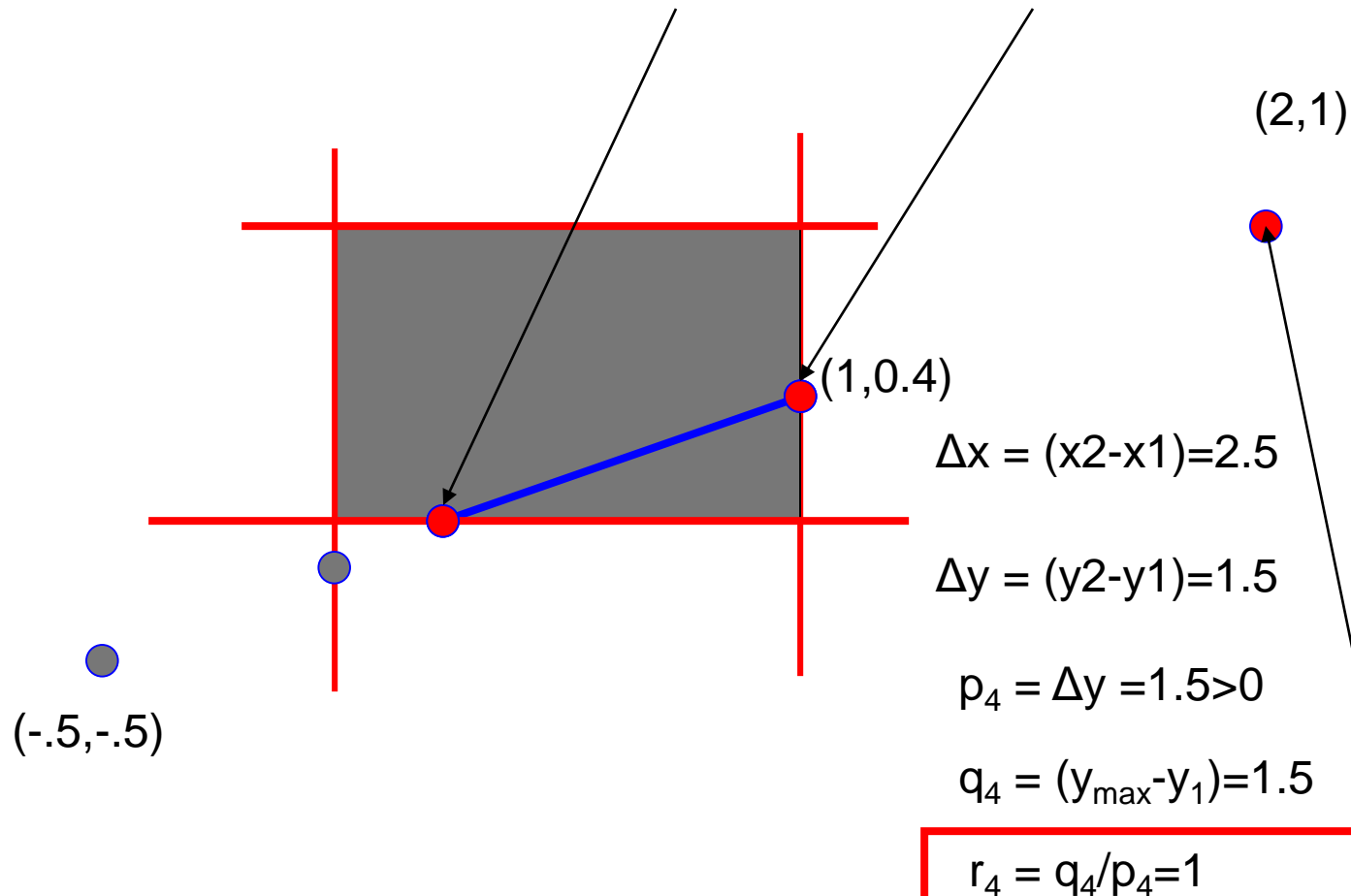
Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0.333, u_2=0.6$)



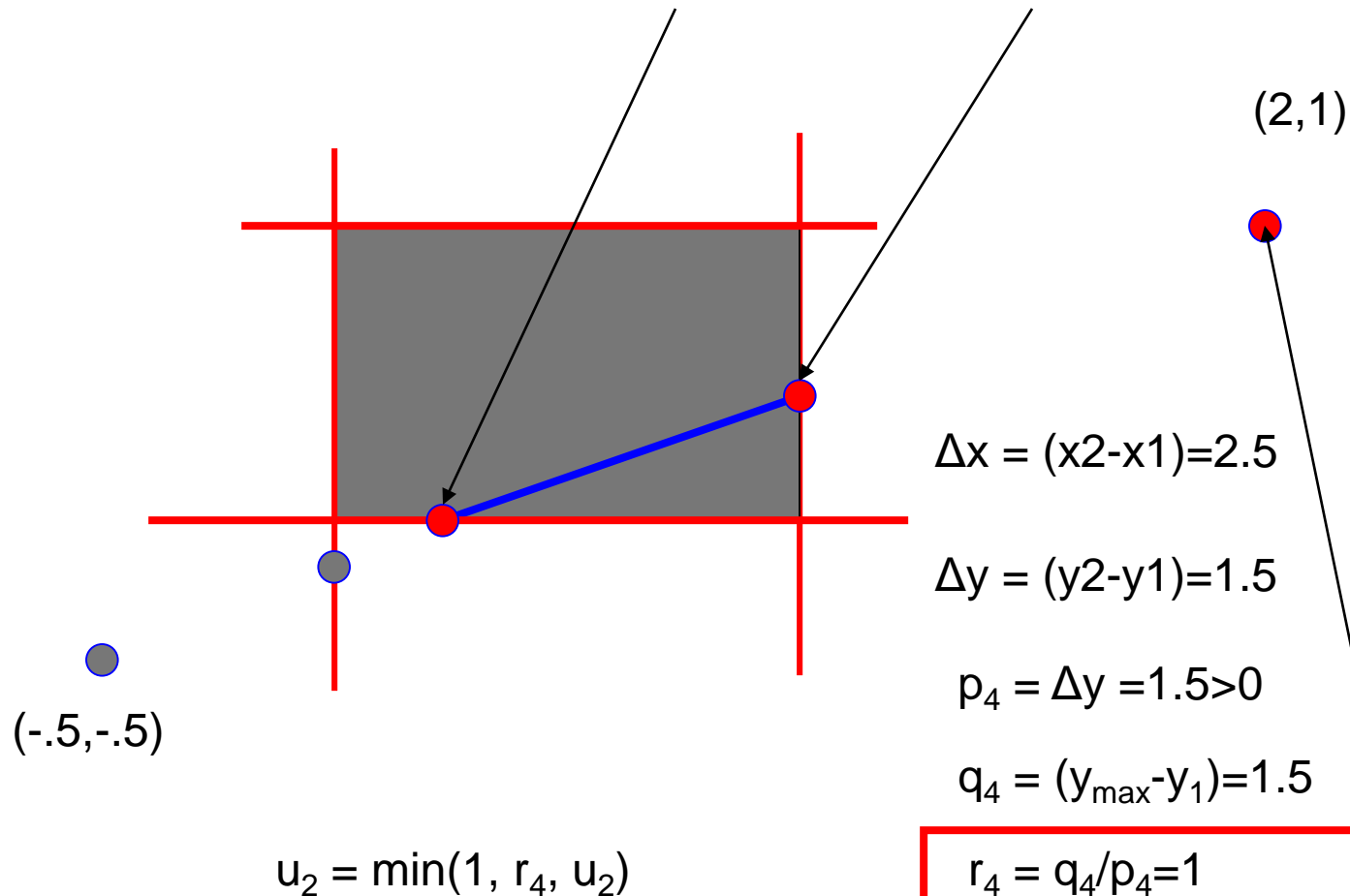
Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0.333, u_2=0.6$)

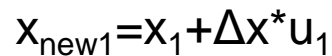


Liang-Barsky Algorithm

- ▶ Current clipped line ($u_1=0.333, u_2=0.6$)



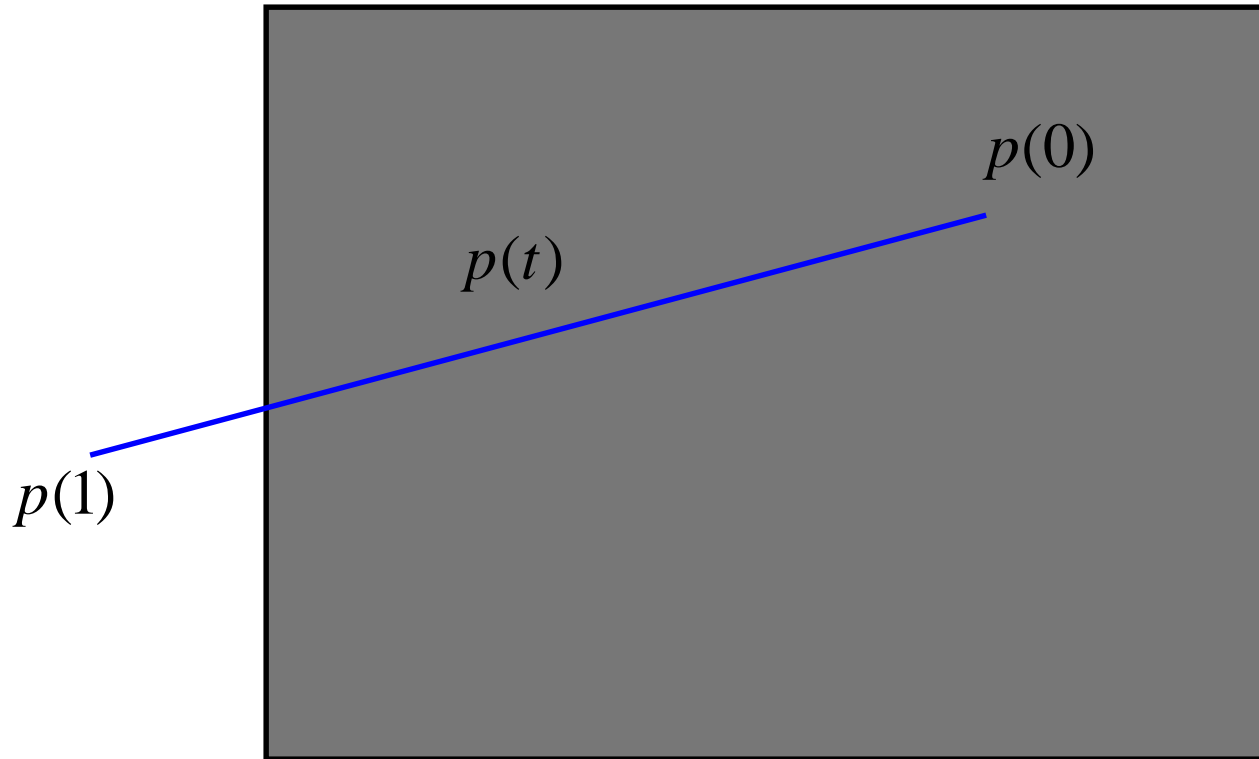
► Check the left edge ($u_1=0.333, u_2=0.6$)



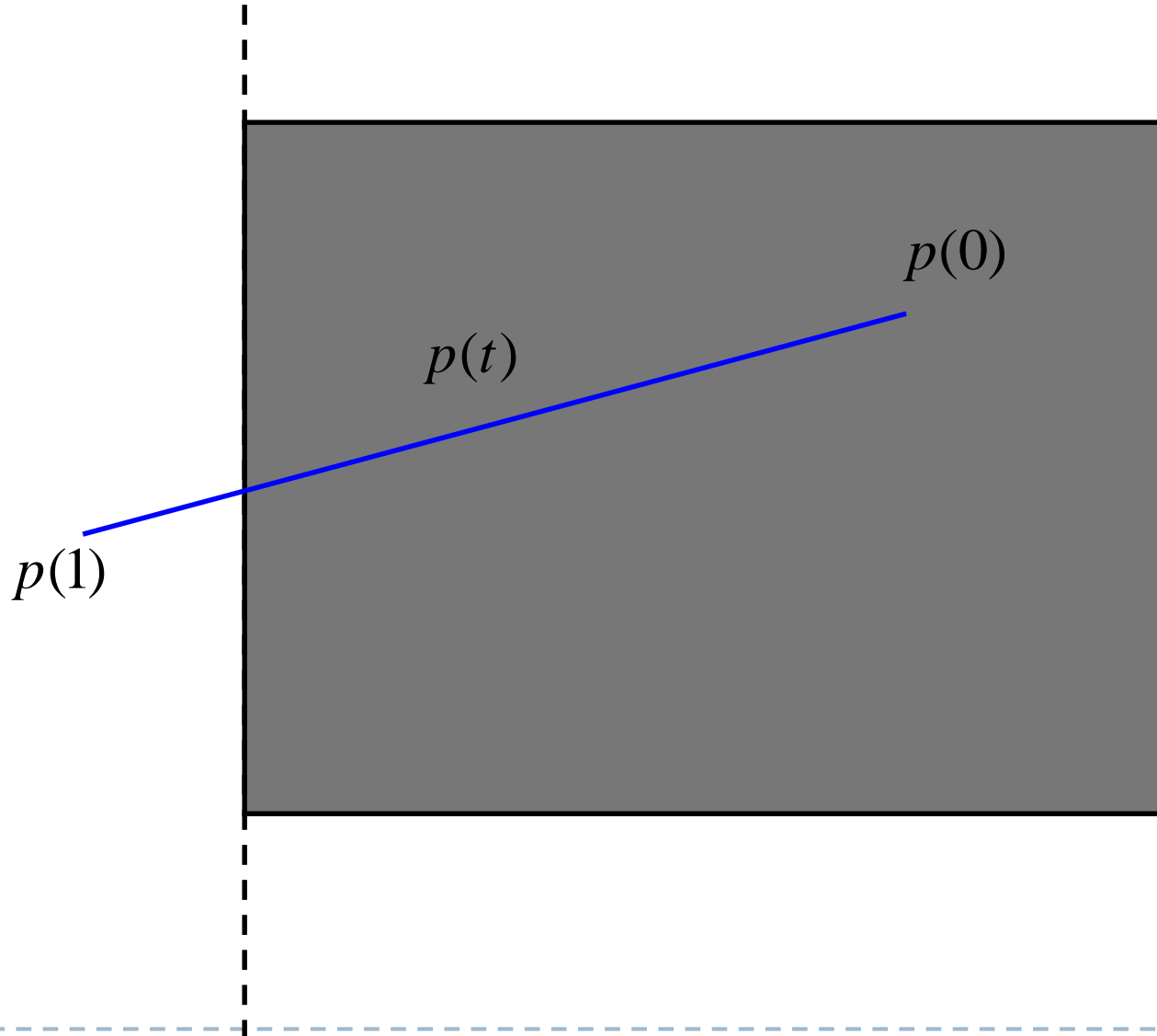
$$x_{\text{new}2} = x_1 + \Delta x^* u_2$$

$$y_{\text{new}2} = y_1 + \Delta y^* u_2$$

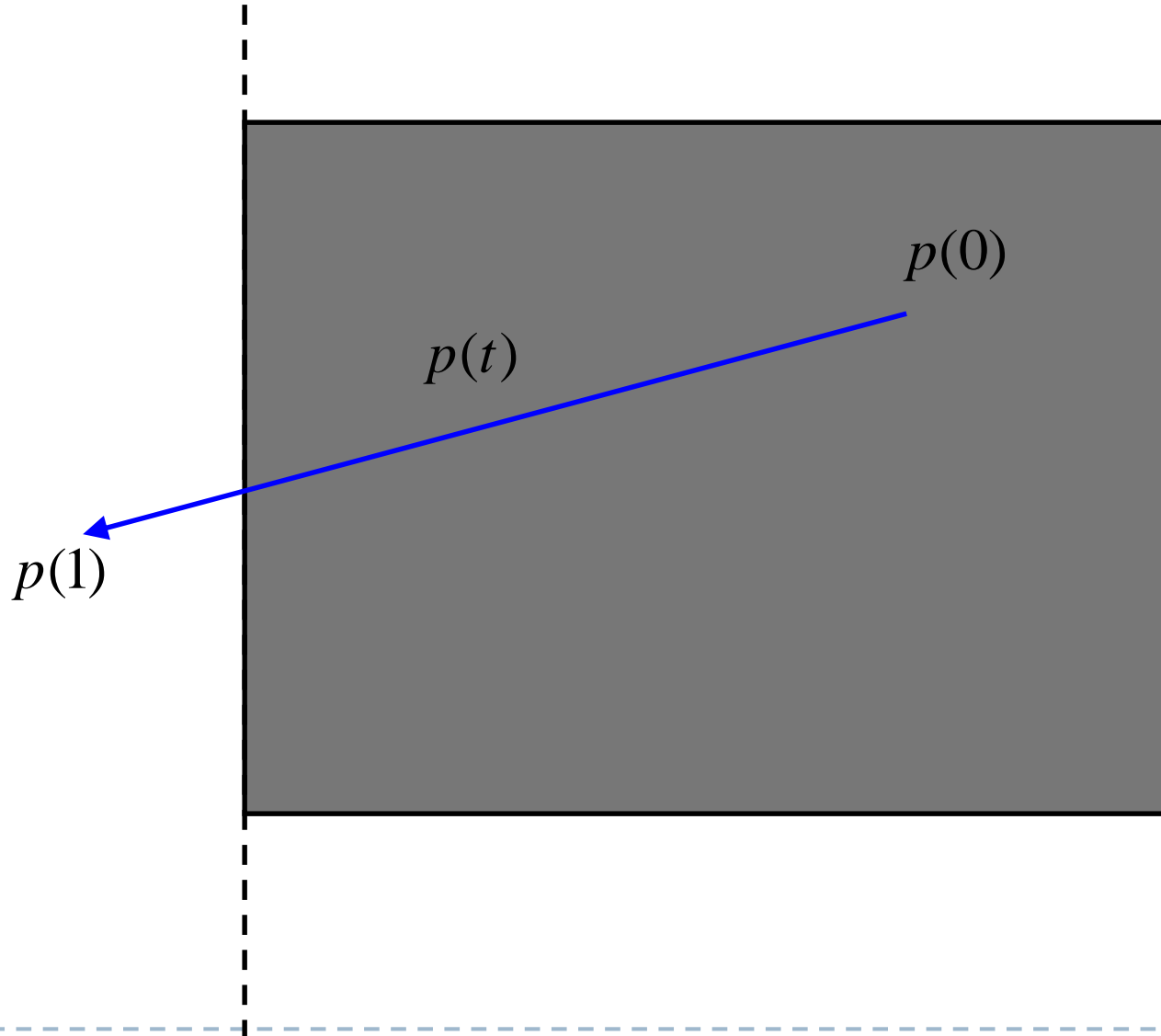
Liang-Barsky Algorithm



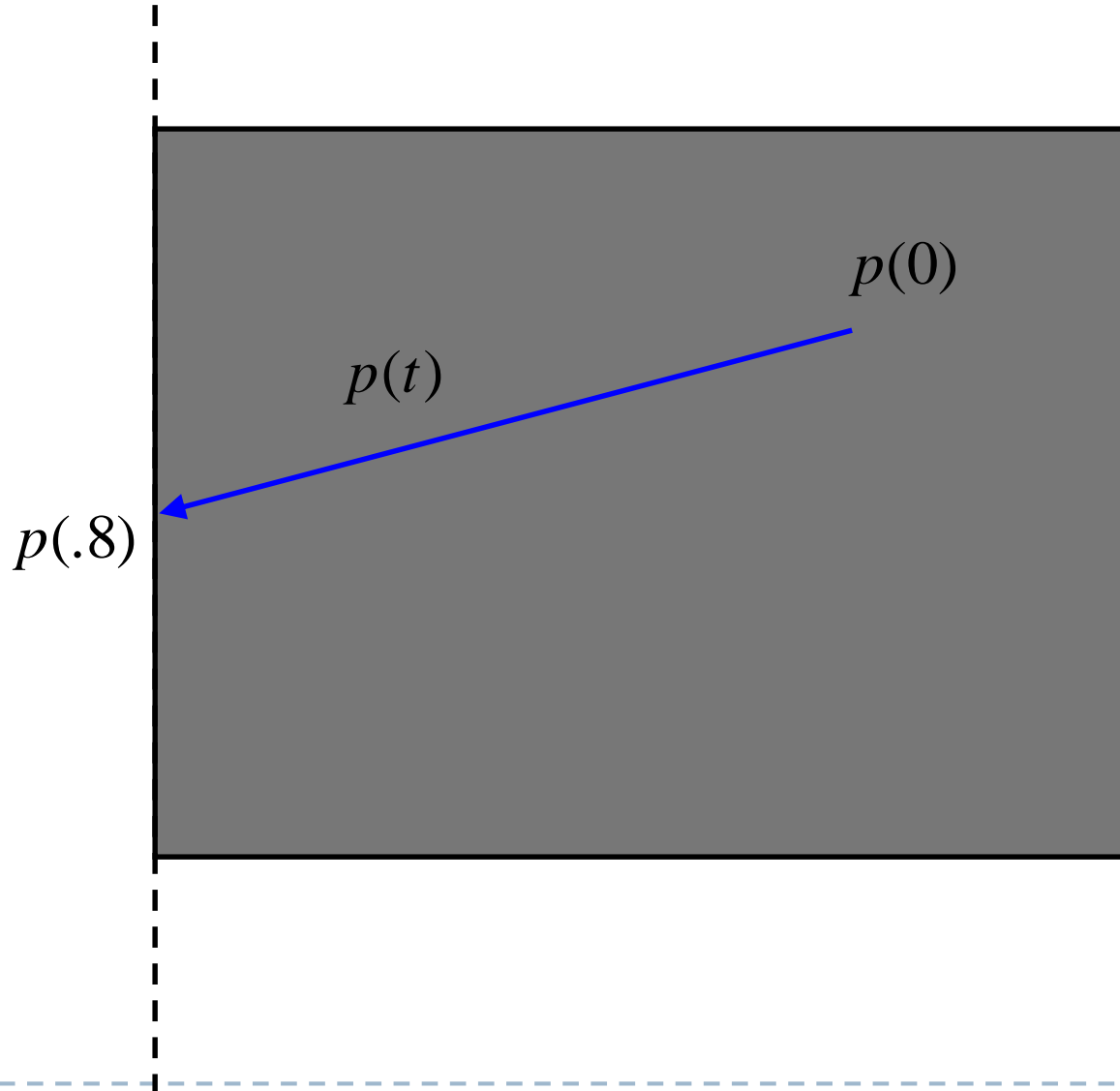
Liang-Barsky Algorithm



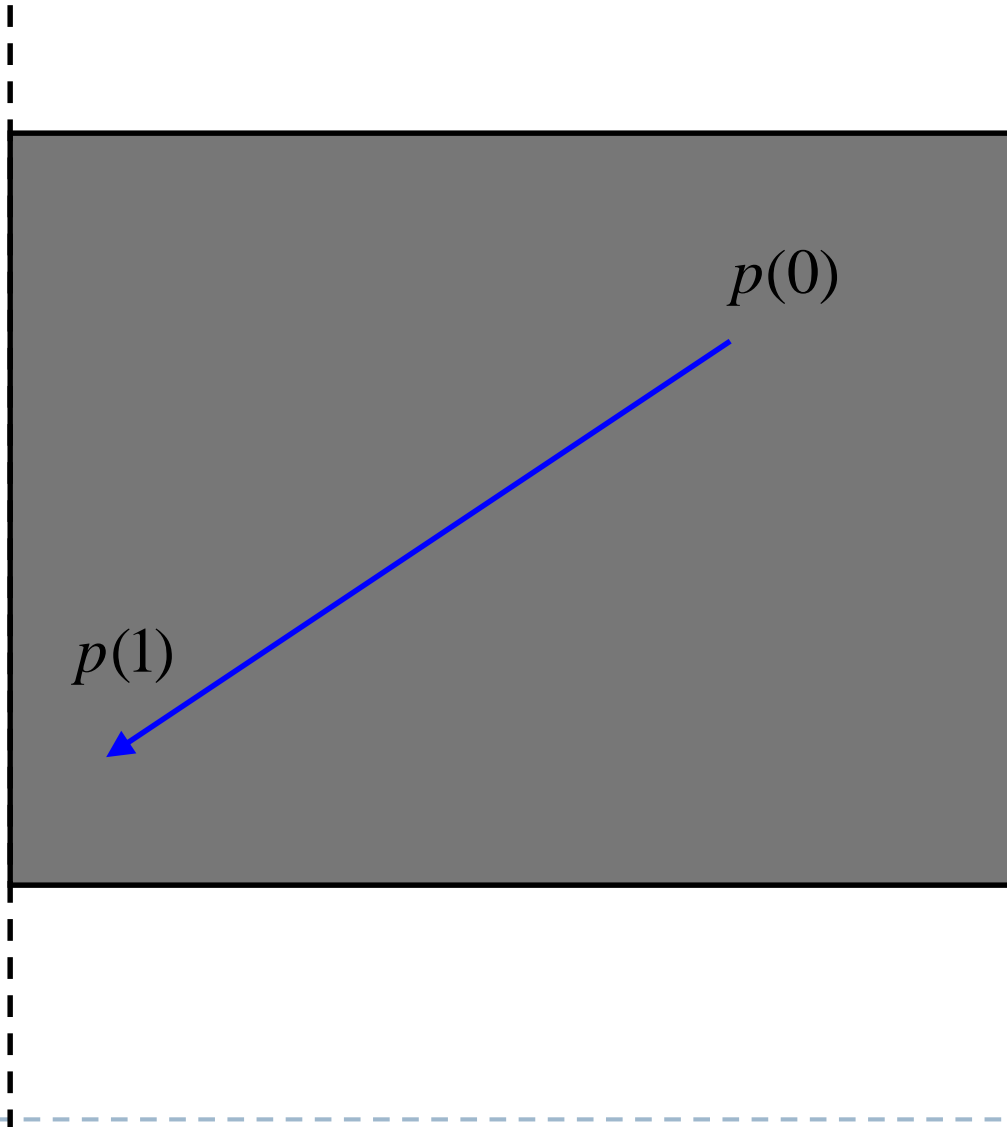
Liang-Barsky Algorithm



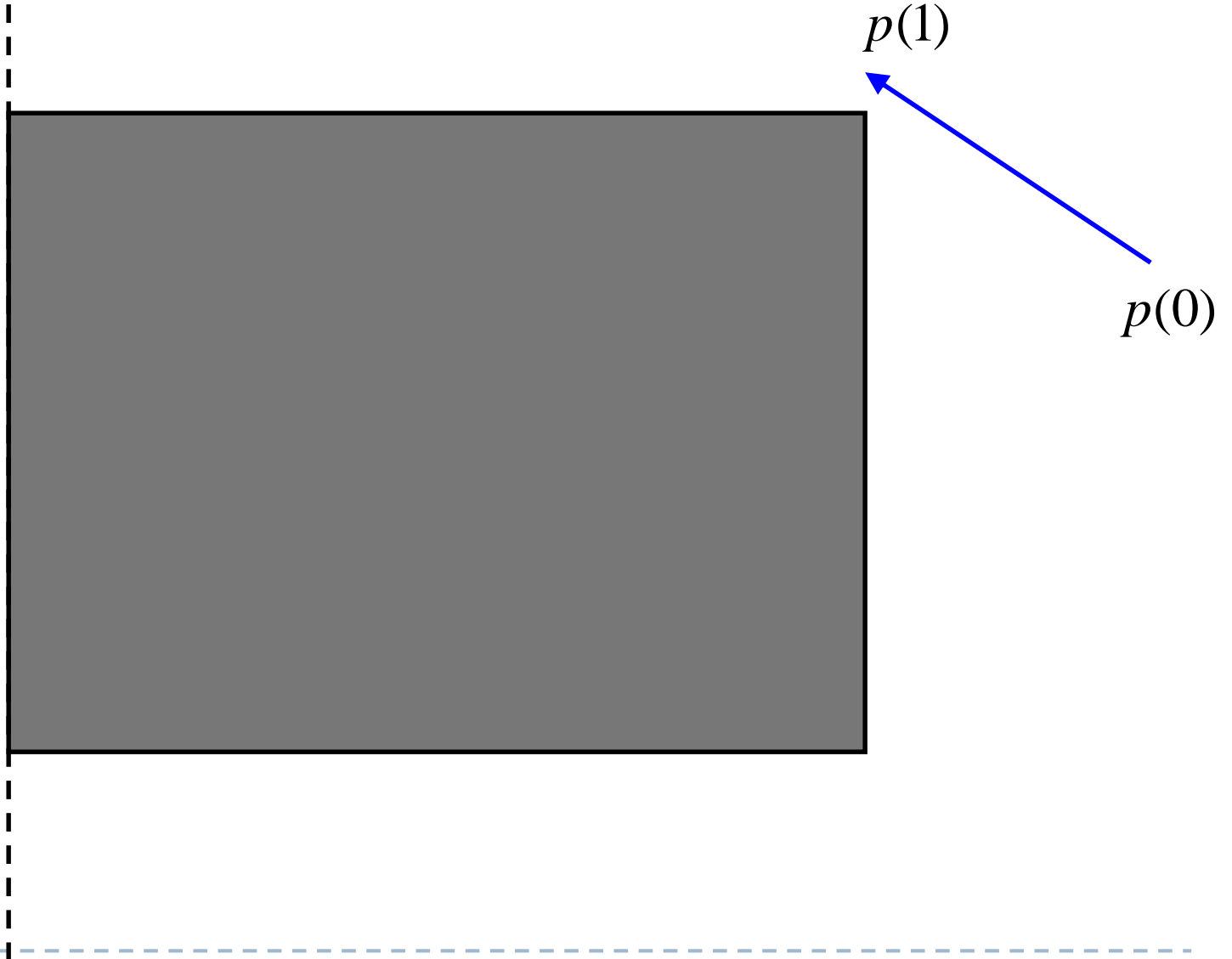
Liang-Barsky Algorithm



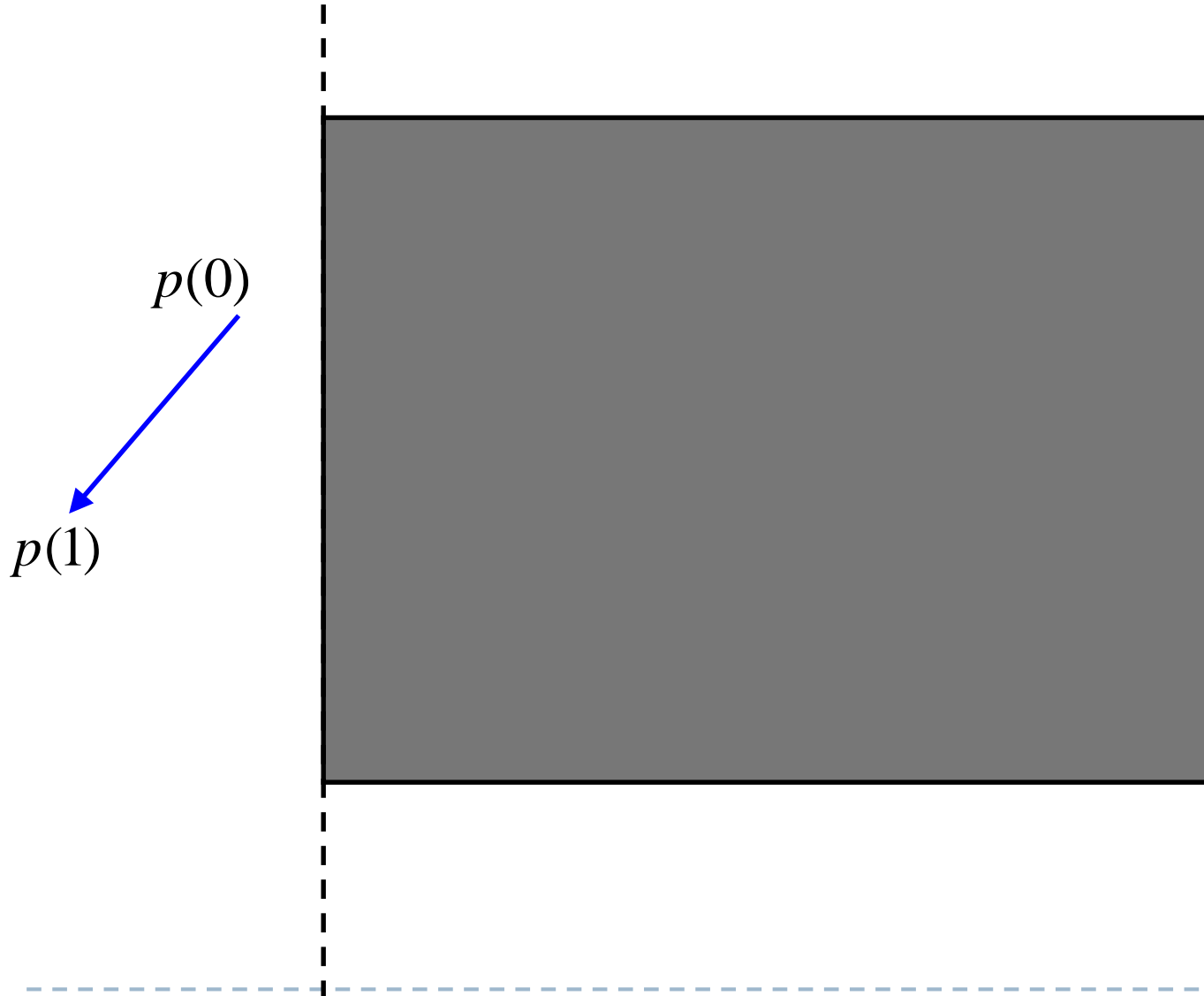
Liang-Barsky Algorithm



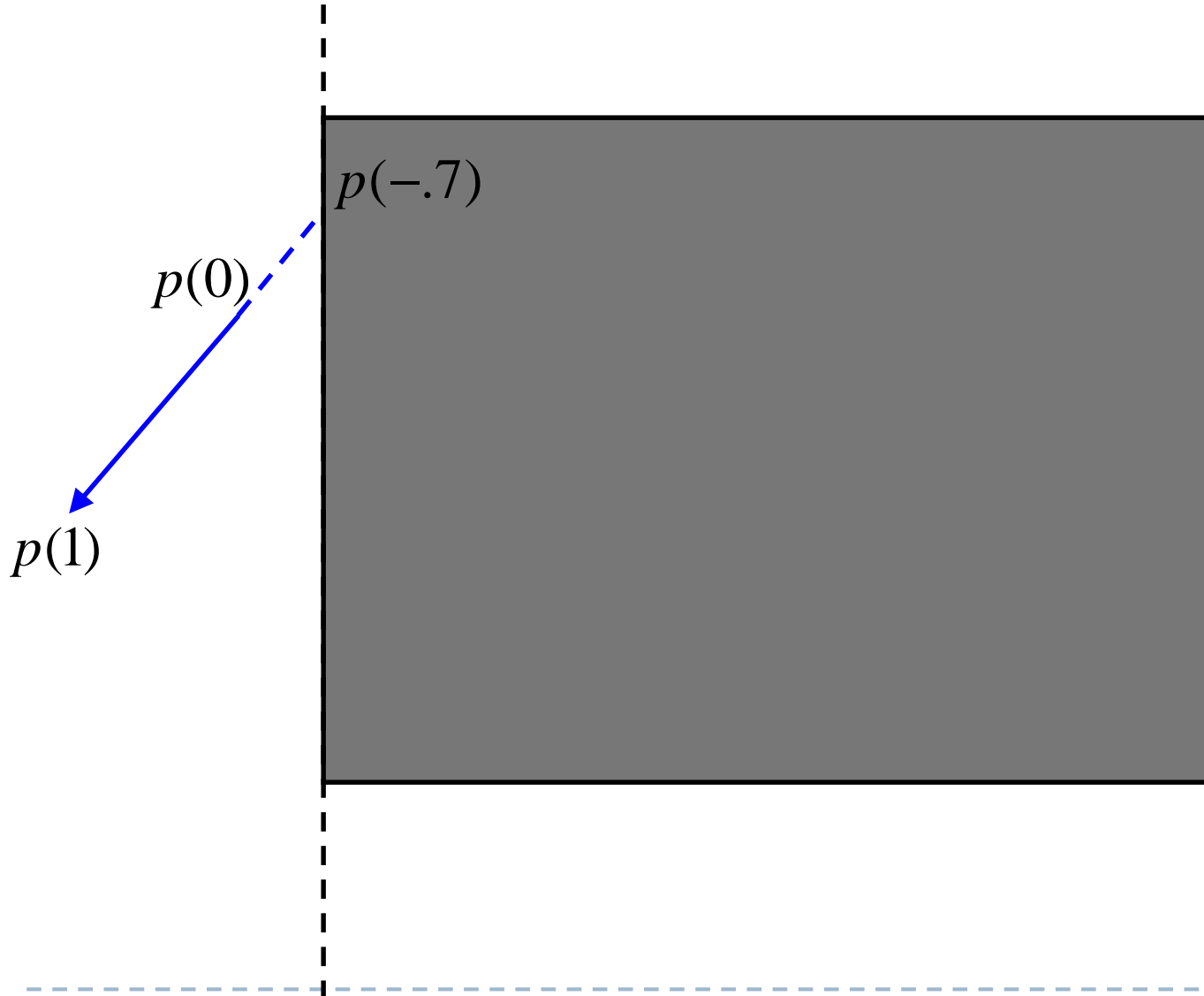
Liang-Barsky Algorithm



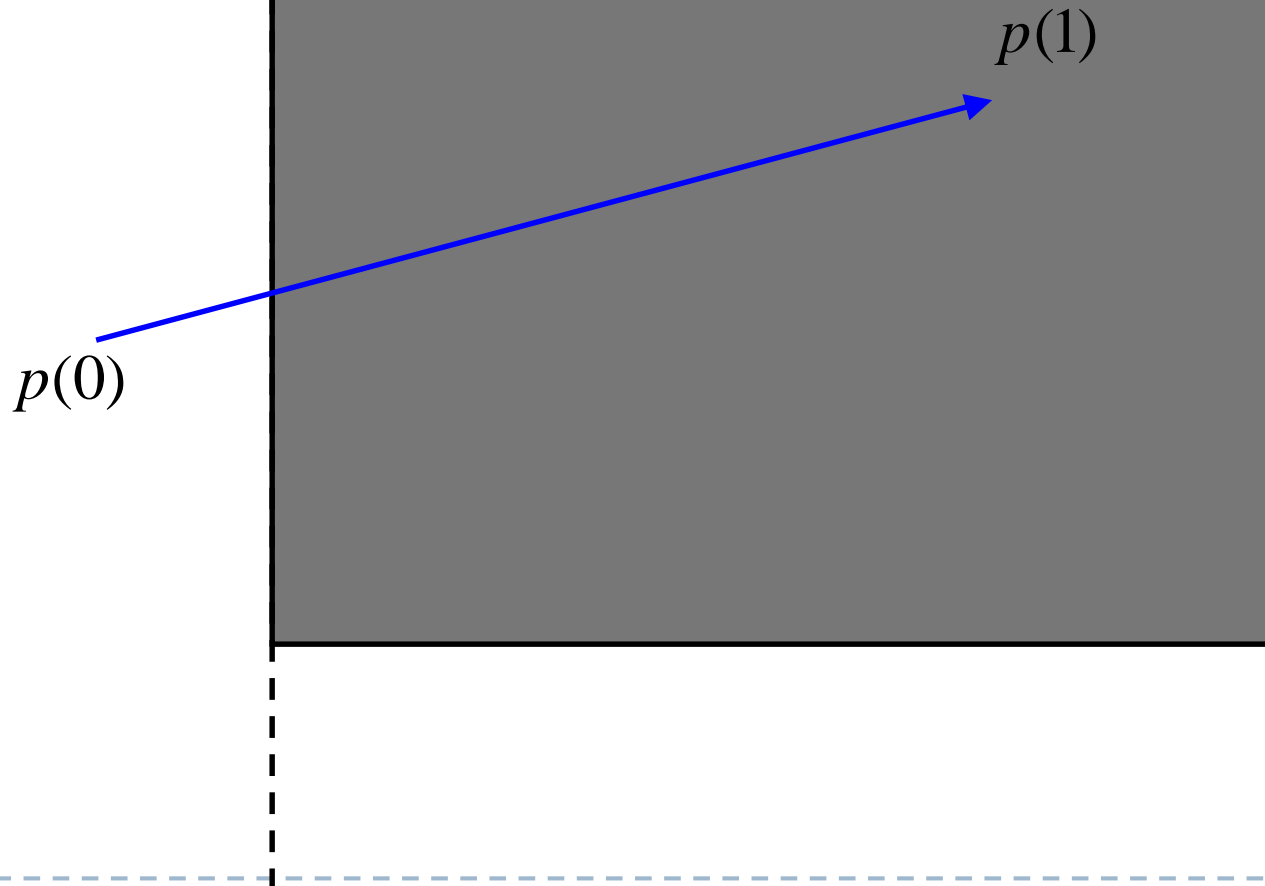
Liang-Barsky Algorithm



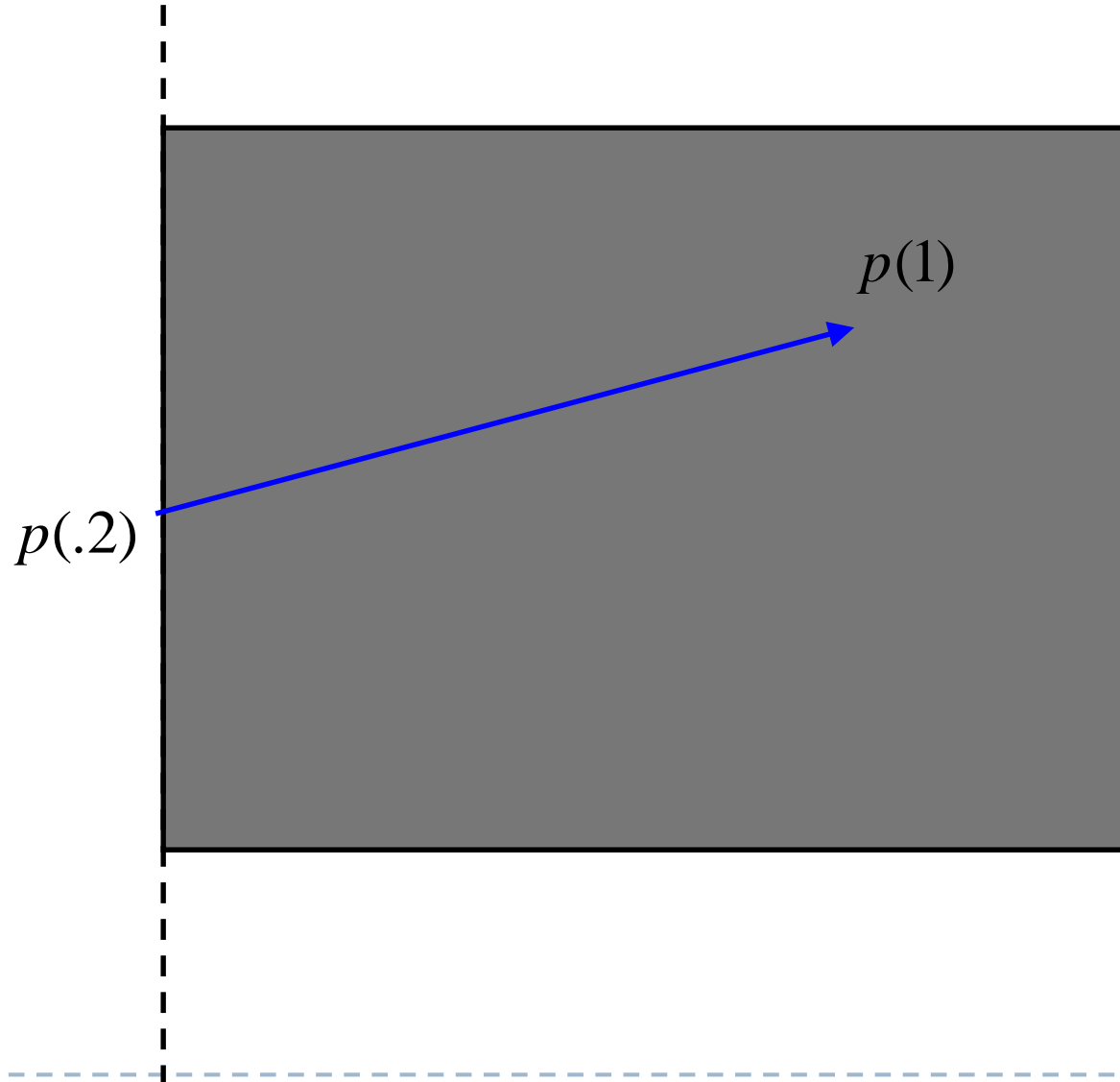
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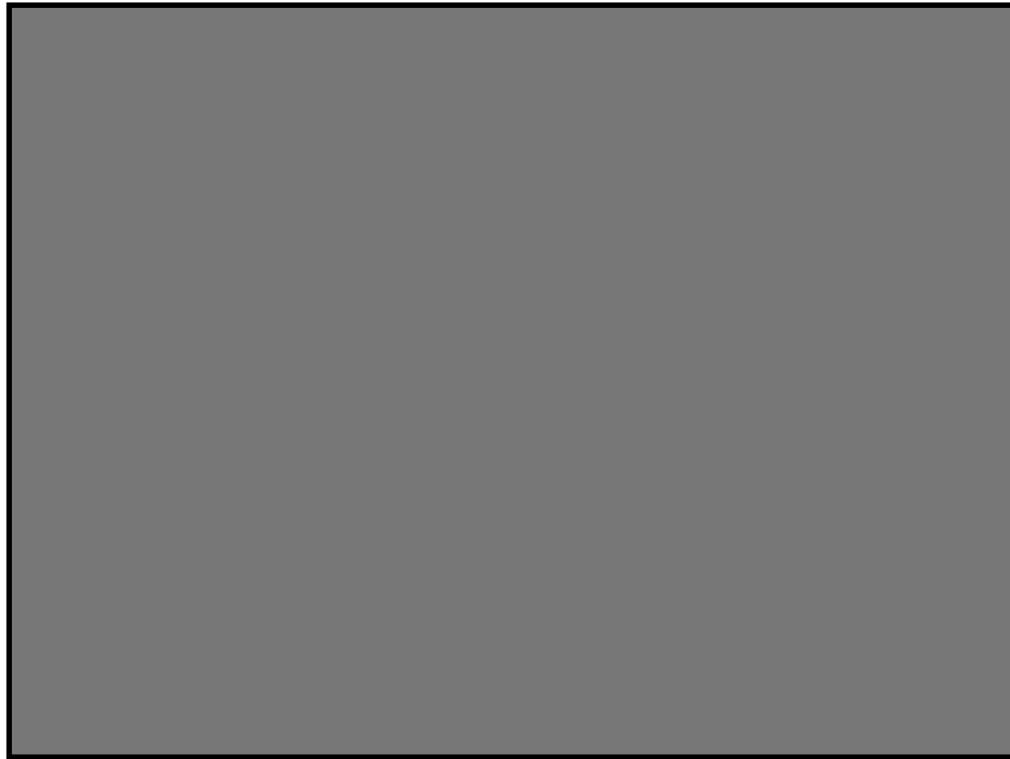
Liang-Barsky Algorithm



Liang-Barsky Algorithm

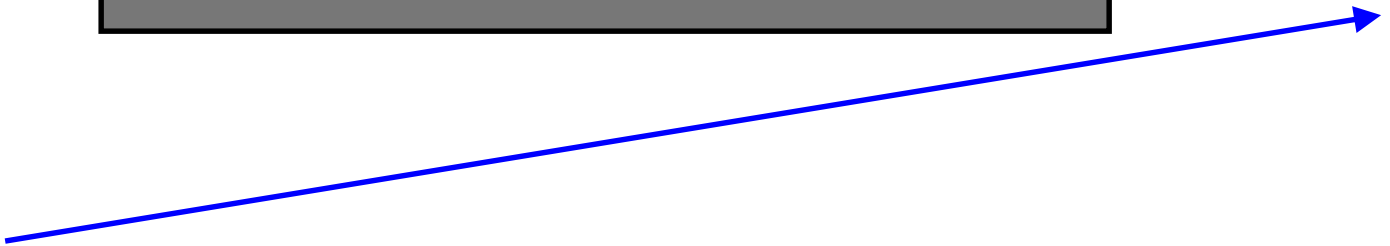


Liang-Barsky Algorithm

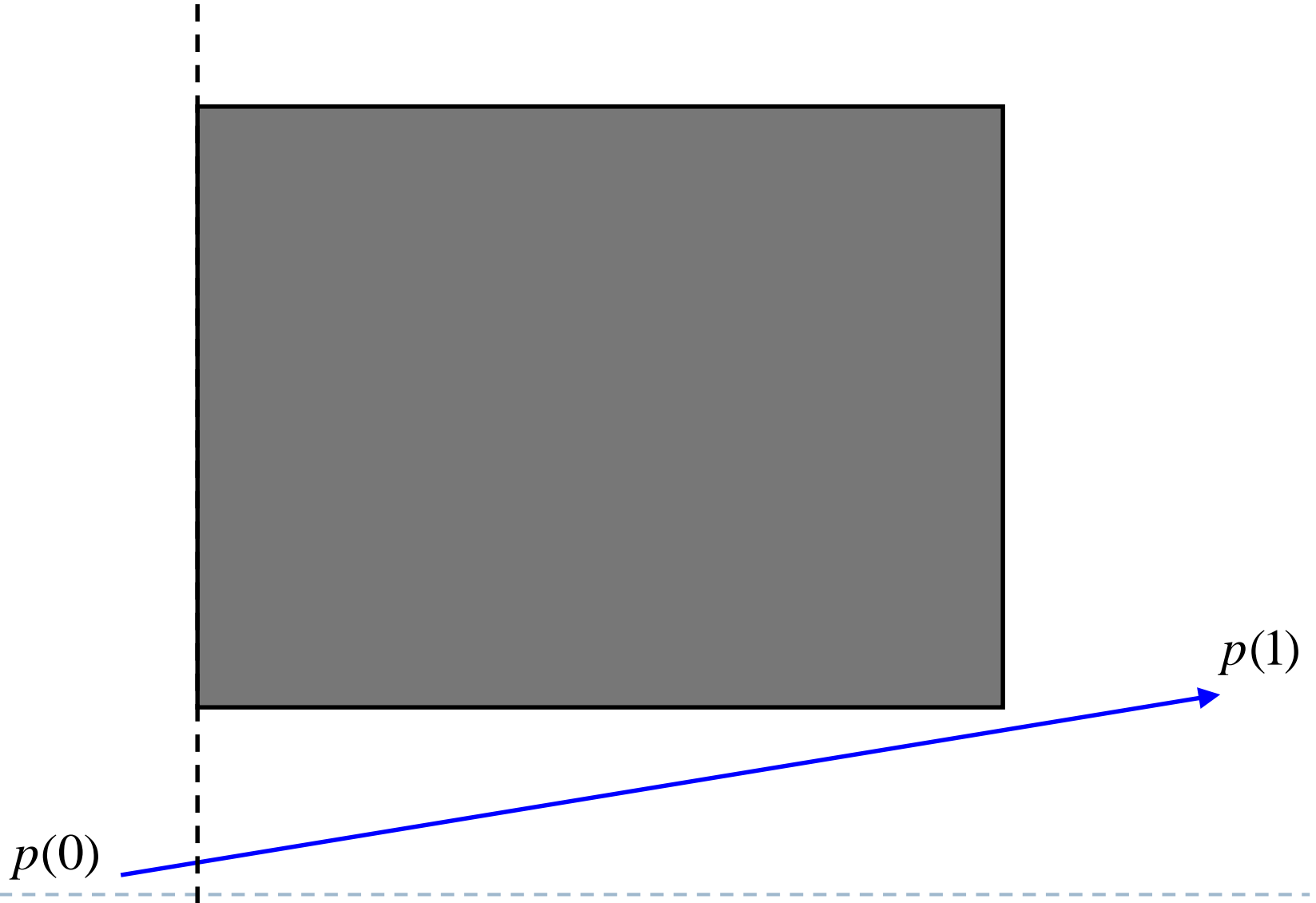


$p(0)$

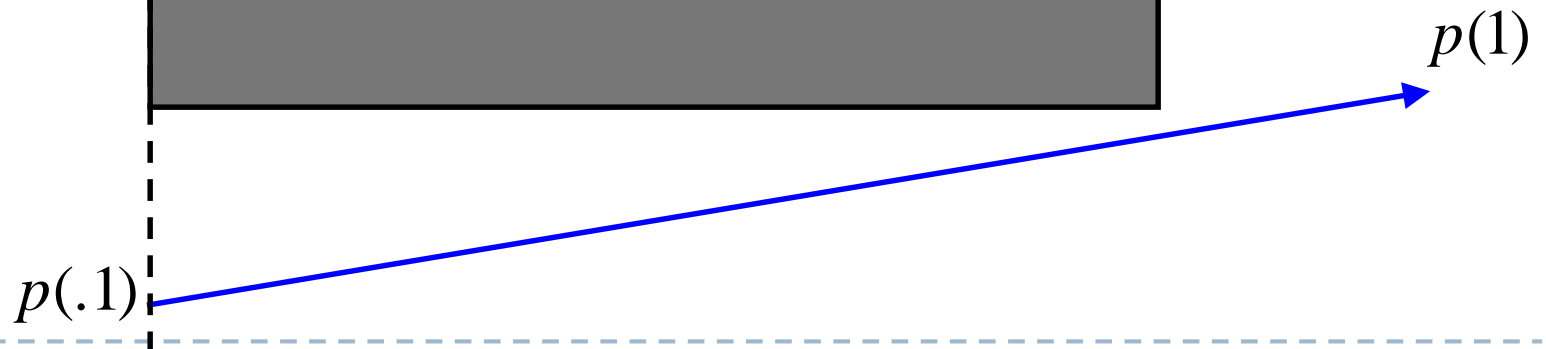
$p(1)$



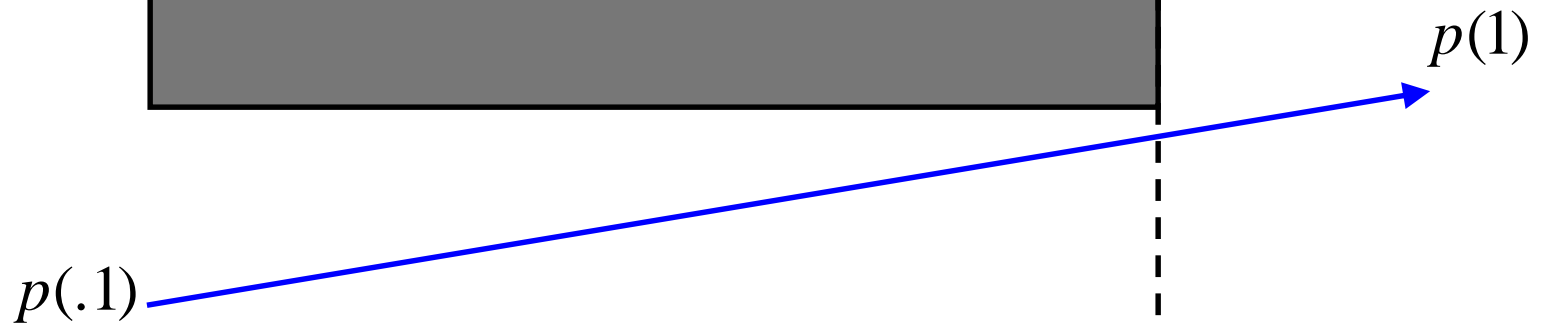
Liang-Barsky Algorithm



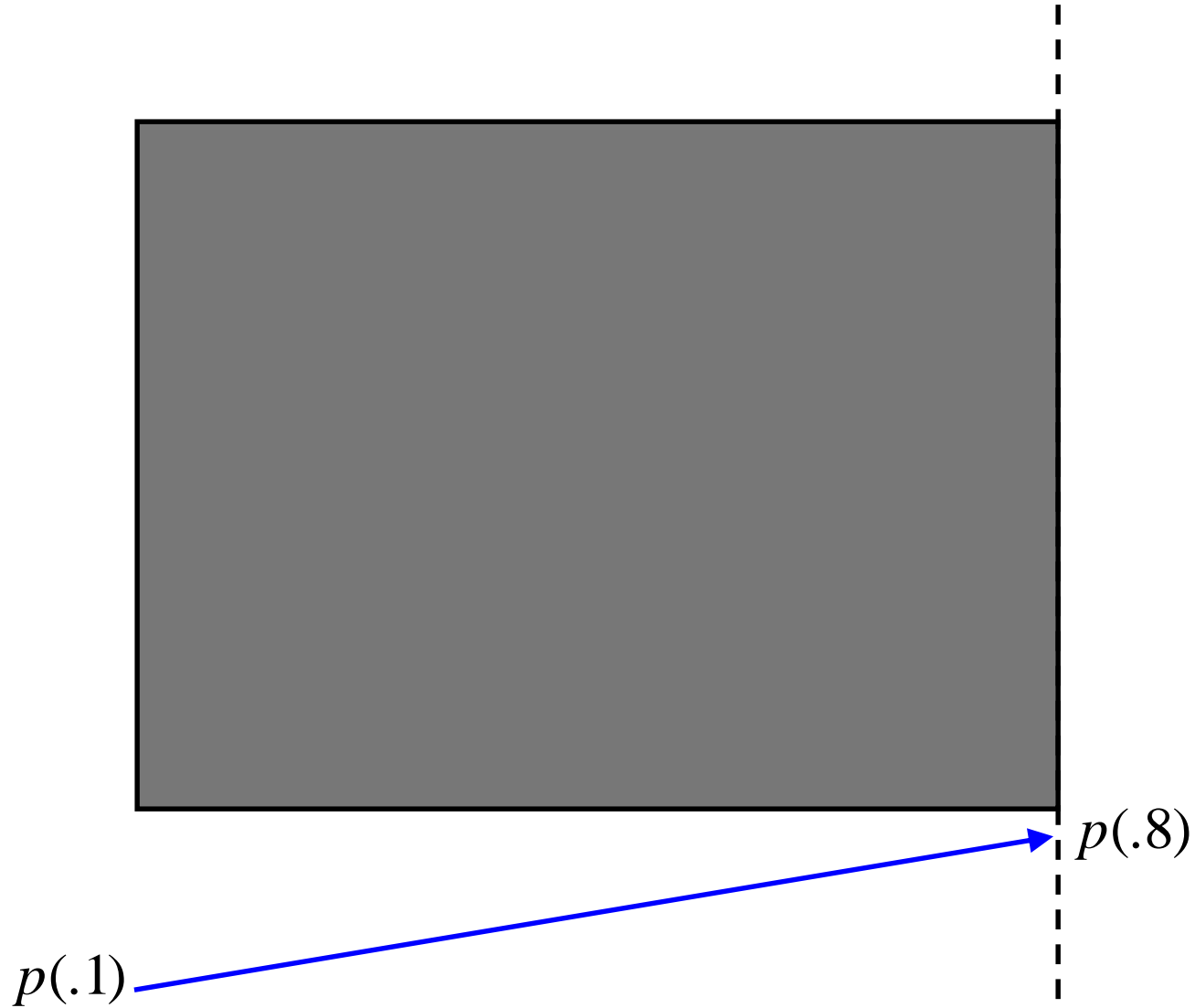
Liang-Barsky Algorithm



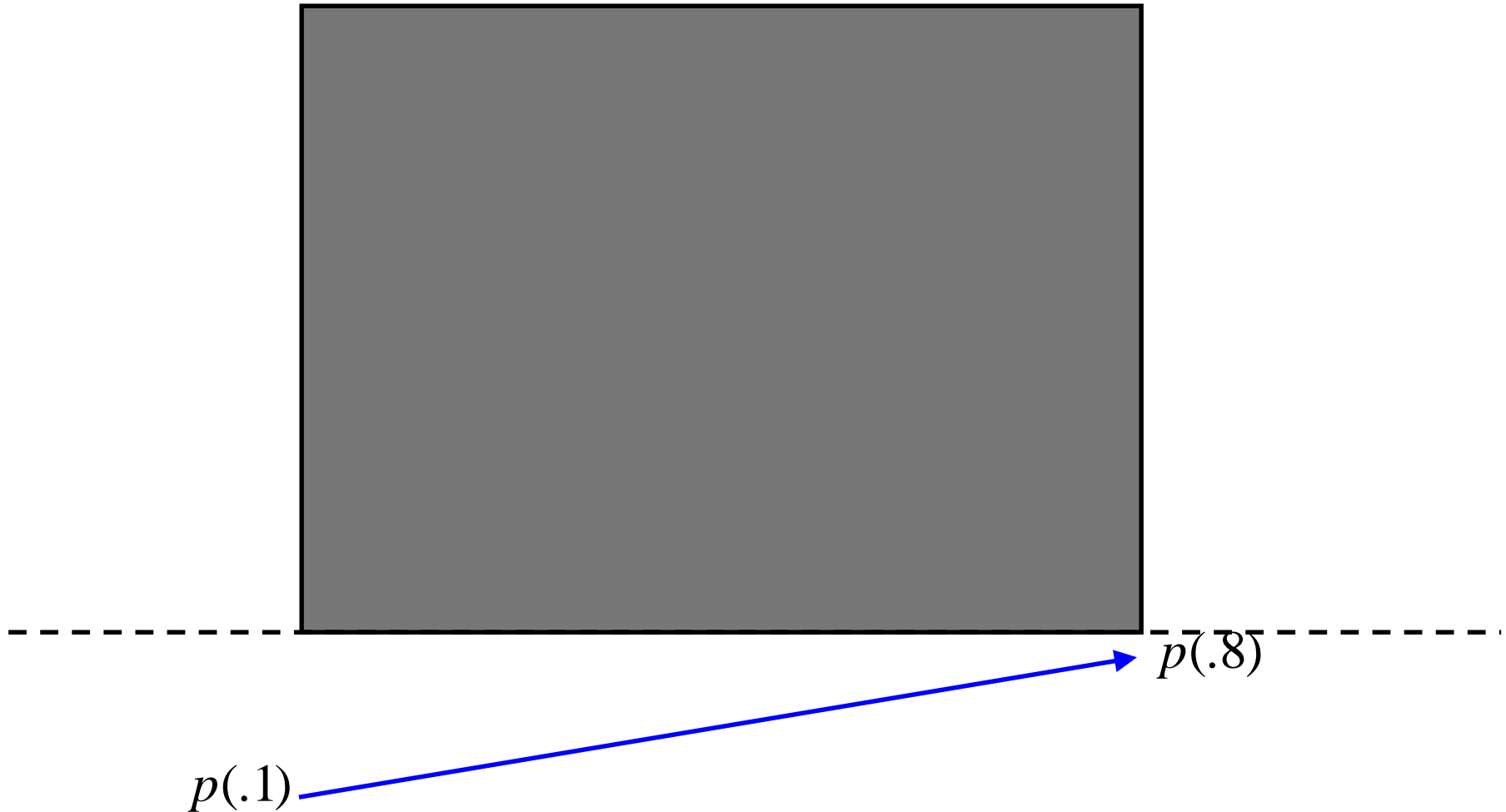
Liang-Barsky Algorithm



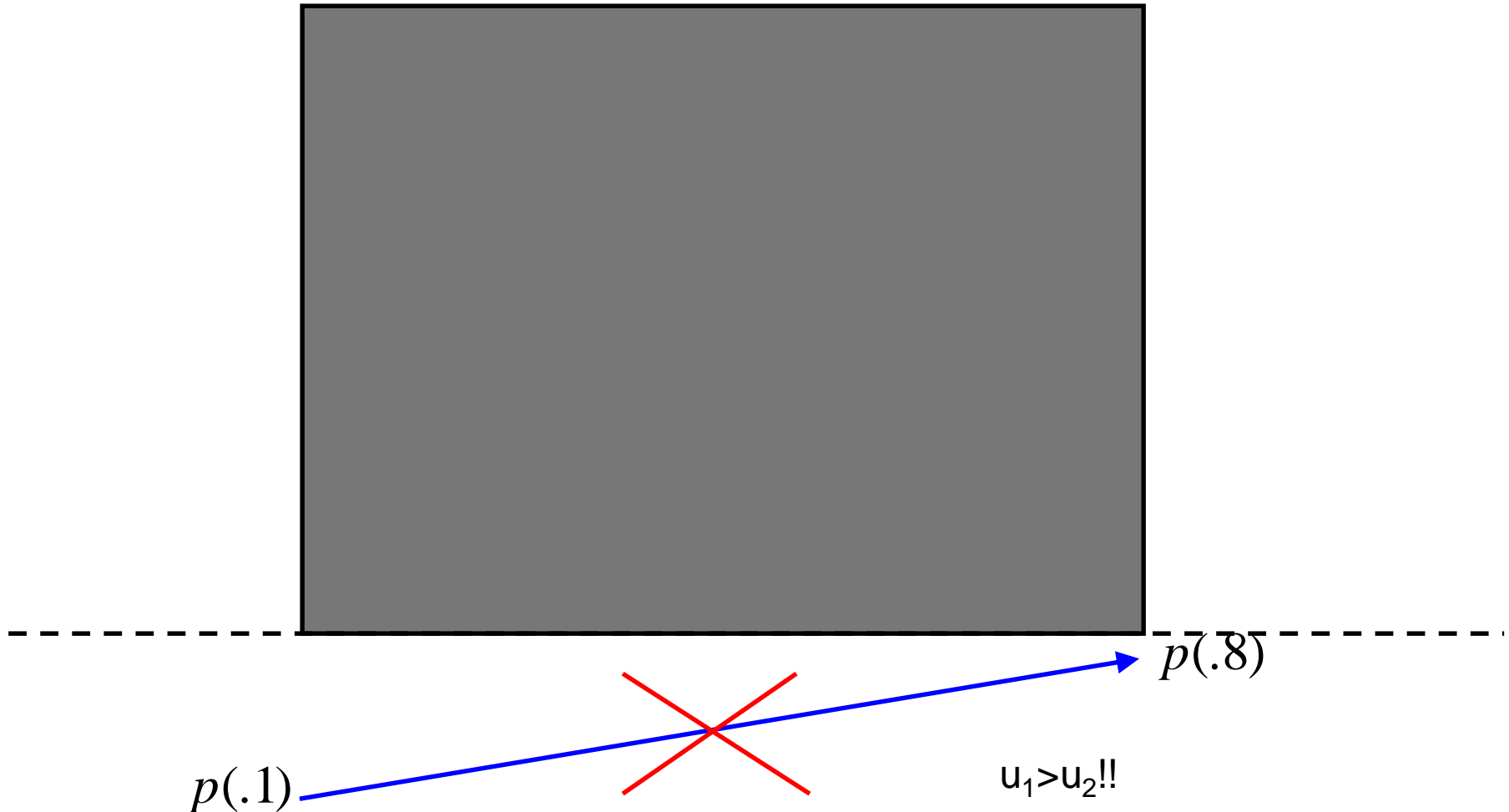
Liang-Barsky Algorithm



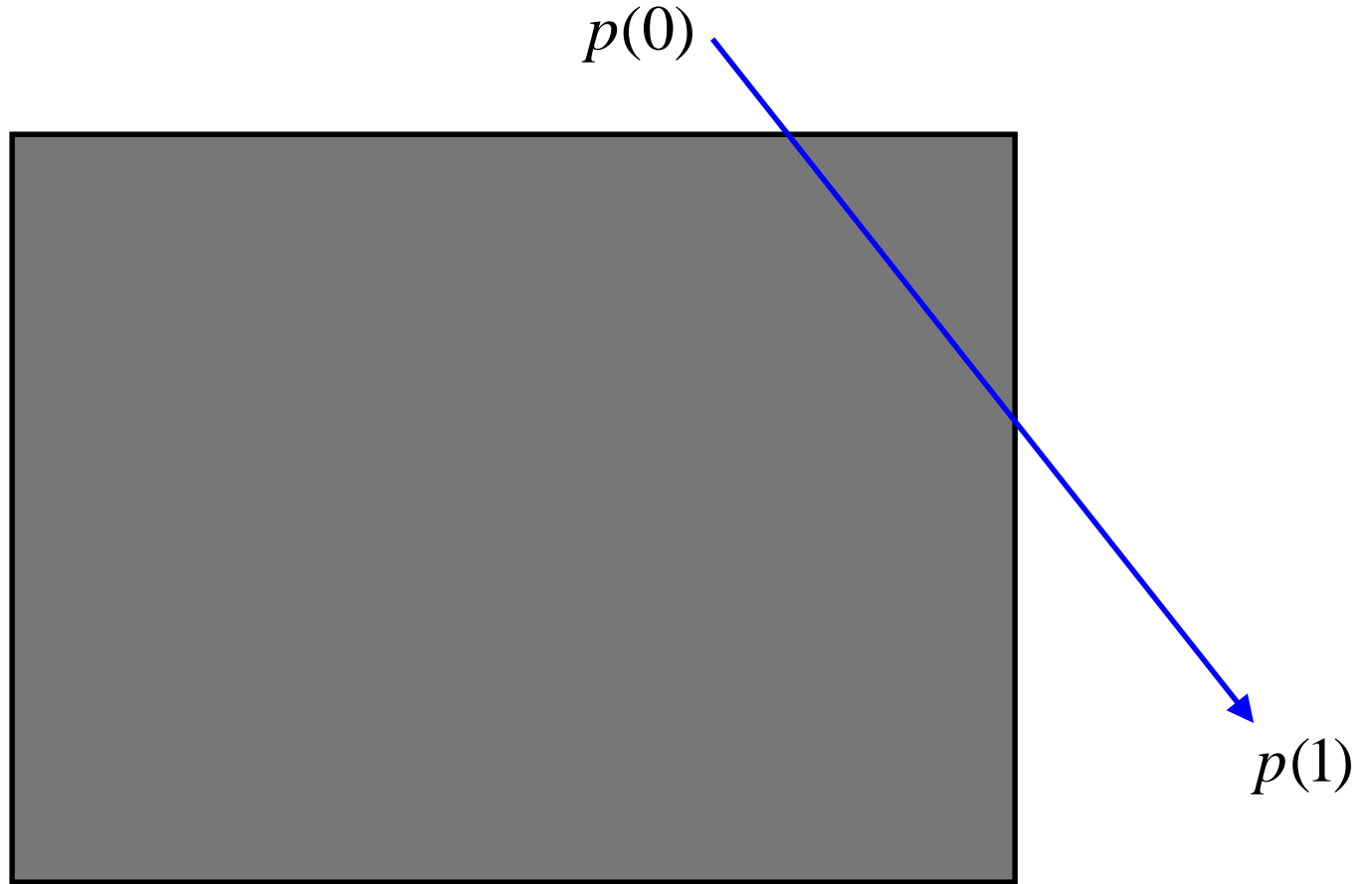
Liang-Barsky Algorithm



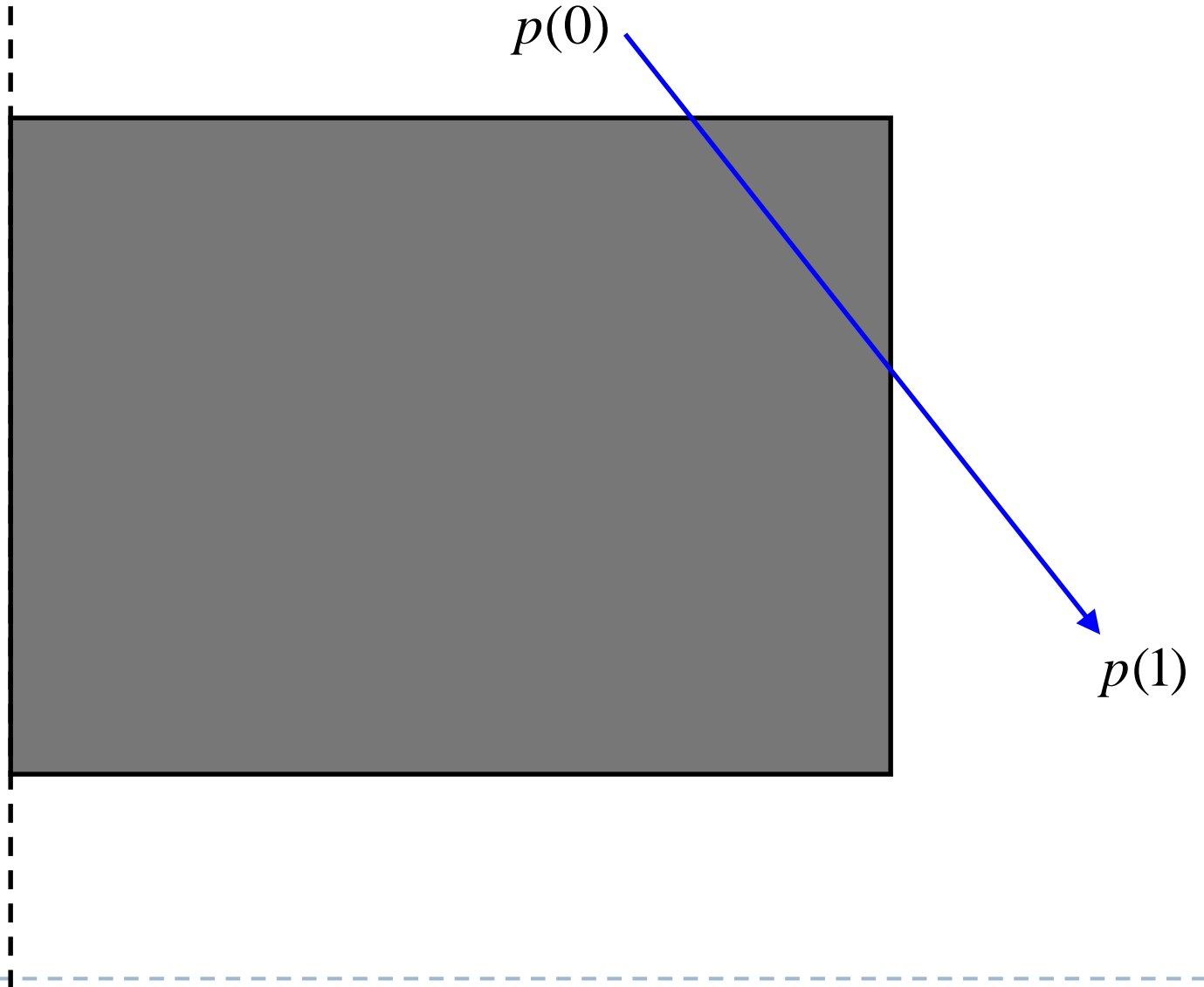
Liang-Barsky Algorithm



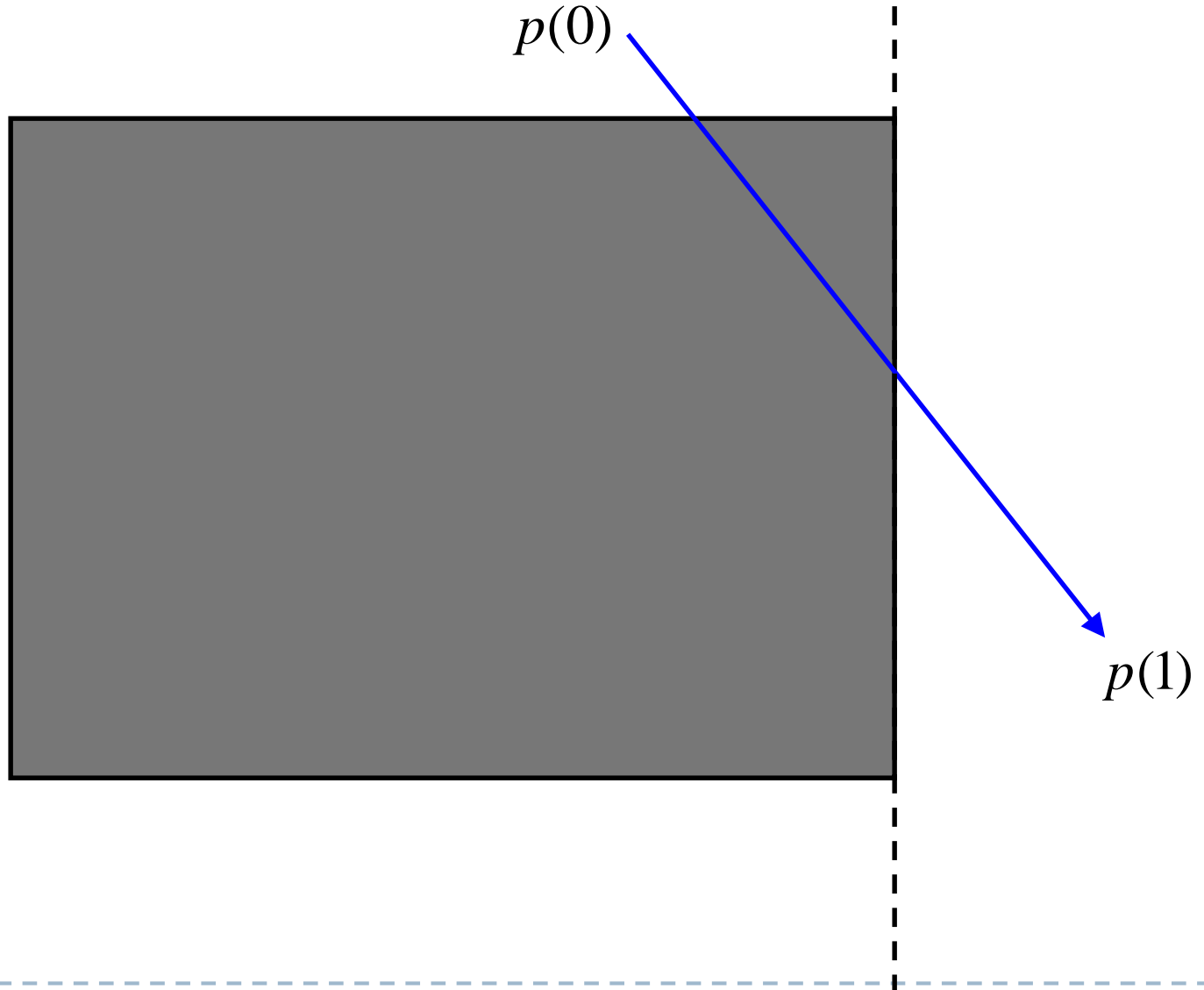
Liang-Barsky Algorithm



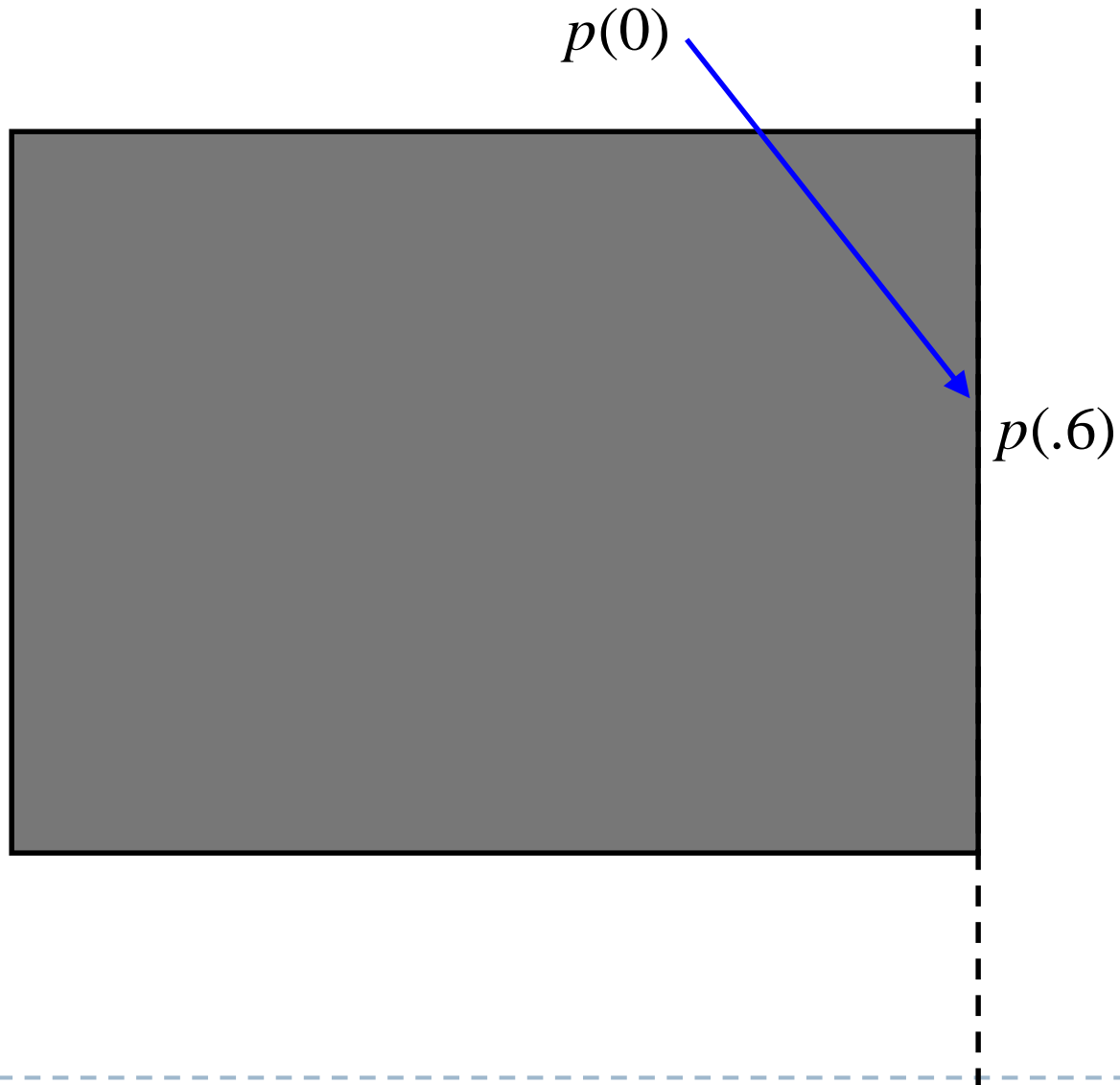
Liang-Barsky Algorithm



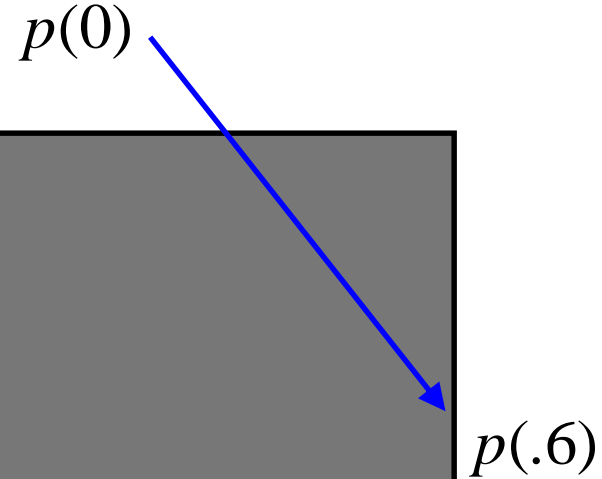
Liang-Barsky Algorithm



Liang-Barsky Algorithm

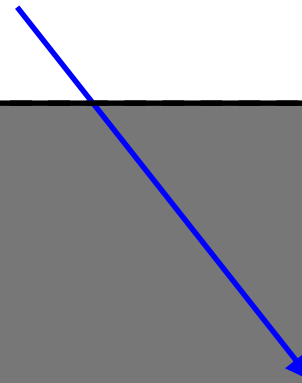


Liang-Barsky Algorithm



Liang-Barsky Algorithm

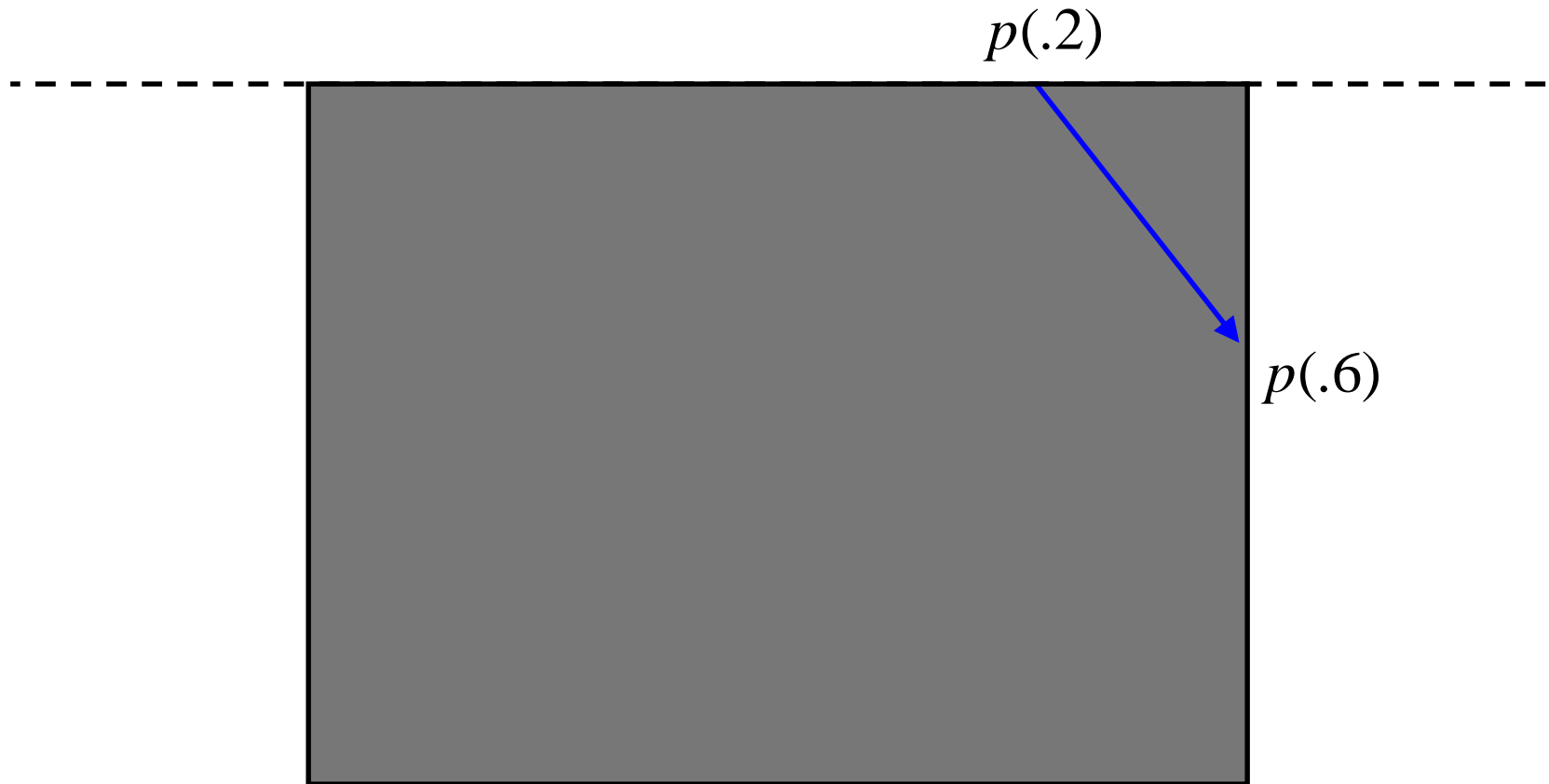
$p(0)$



$p(.6)$



Liang-Barsky Algorithm



Liang-Barsky Algorithm

for each line segment to be clipped

Pre-calculate p_k and q_k ;

if $P_1 = P_0$ **then** line is degenerate so clip as a point;

else

begin

$u_1 = 0$; $u_2 = 1$;

for each candidate intersection with a clip edge

if $p_k = 0$ **then** {Ignore edges parallel to line}

begin

calculate u ; {of line and clip edge intersection}

use sign of p_k to categorize as P_{start} or P_{end} ;

if P_{start} **then** $u_1 = \max(0, u_1, u)$;

if P_{end} **then** $u_2 = \min(1, u_2, u)$;

end

if $u_1 > u_2$ **then** return **nil**

else return $P(u_1)$ and $P(u_2)$ as true clip intersections

end



Liang-Barsky Algorithm

- ▶ Faster than Cohen-Sutherland
- ▶ Extension to 3D is easy
 - Parametric representation for 3D lines
 - Compute u_1, u_2 based on the intersection between line and plane

Comparison

▶ Cohen-Sutherland

- ▶ Repeated clipping is expensive
- ▶ Best used when trivial acceptance and rejection is possible for most lines

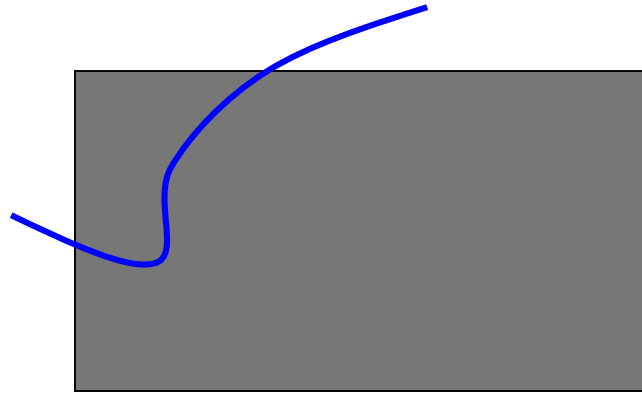
▶ Liang-Barsky

- ▶ Computation of t-intersections is cheap (only one division)
- ▶ Computation of (x,y) clip points is only done once
- ▶ Algorithm doesn't consider trivial accepts/rejects
- ▶ Best when many lines must be clipped

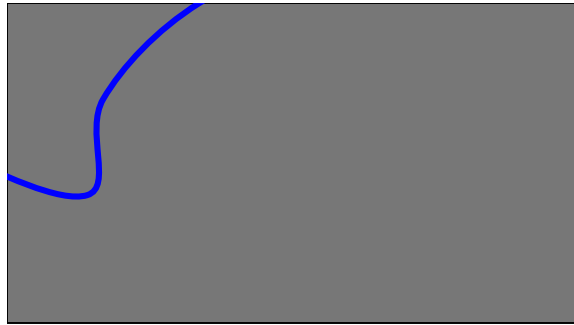
▶ Nicholl et al.: Fastest, but doesn't do 3D

Αποκοπή καμπύλων

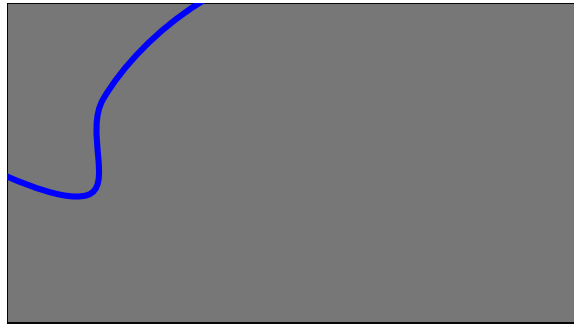
Curve Clipping



Curve Clipping



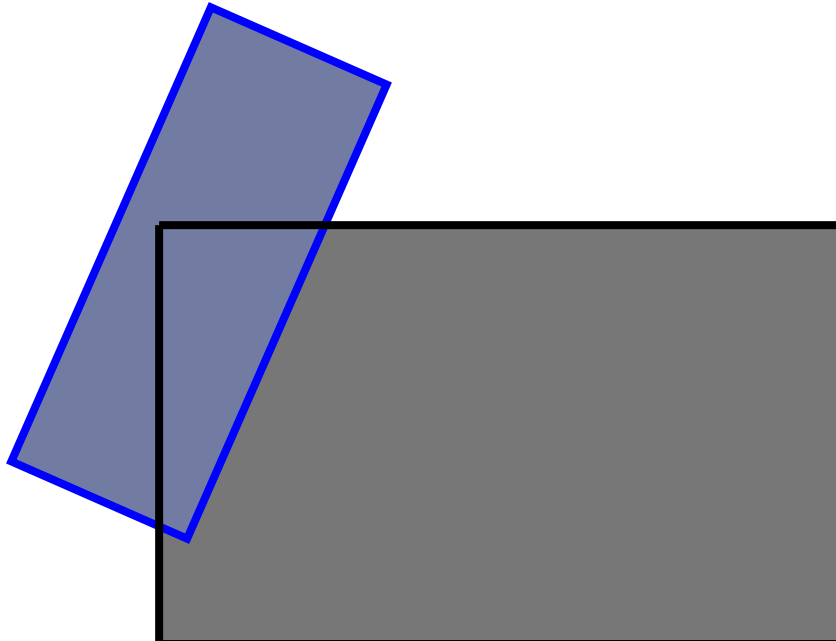
Curve Clipping



- ▶ Approximate a curve using a set of straight-line segments
- ▶ Apply line clipping for curve clipping

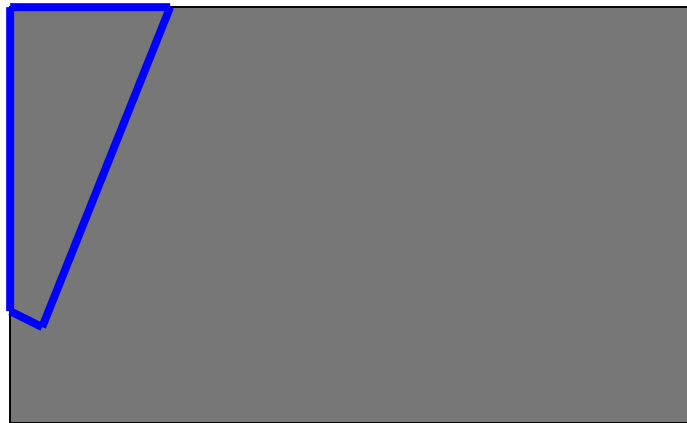
Next Lecture

- Polygon fill-area clipping



Next Lecture

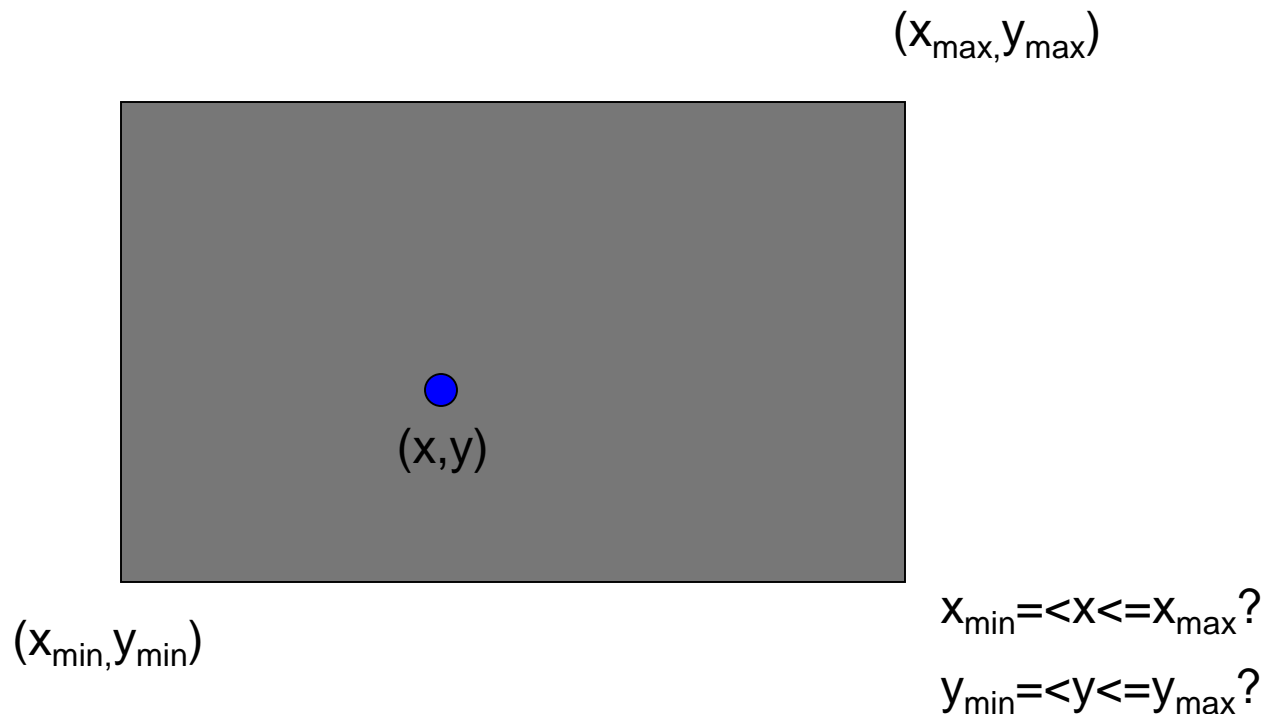
- ▶ Polygon fill-area clipping



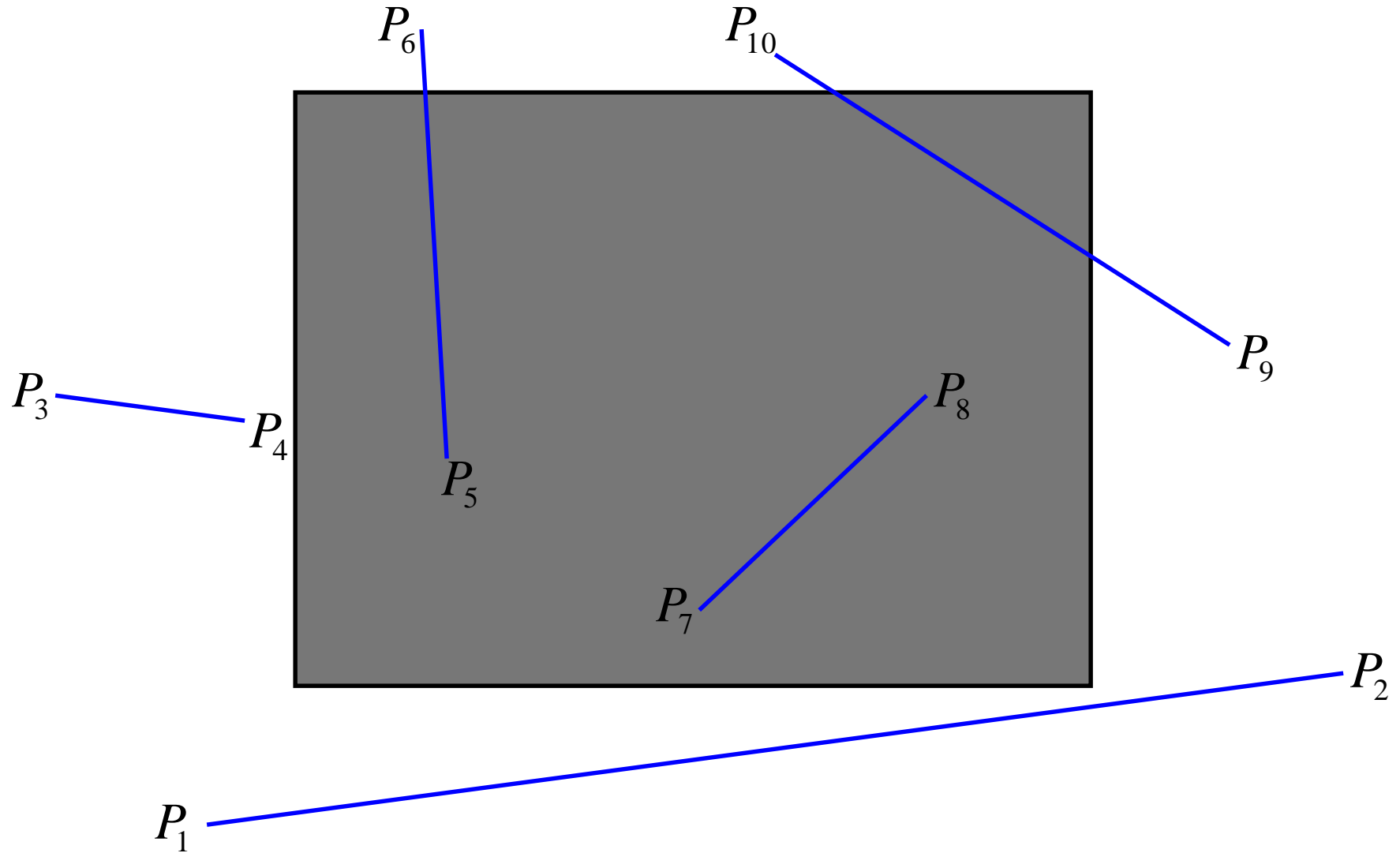
Αποκοπή πολυγώνων

Review: Clipping Points

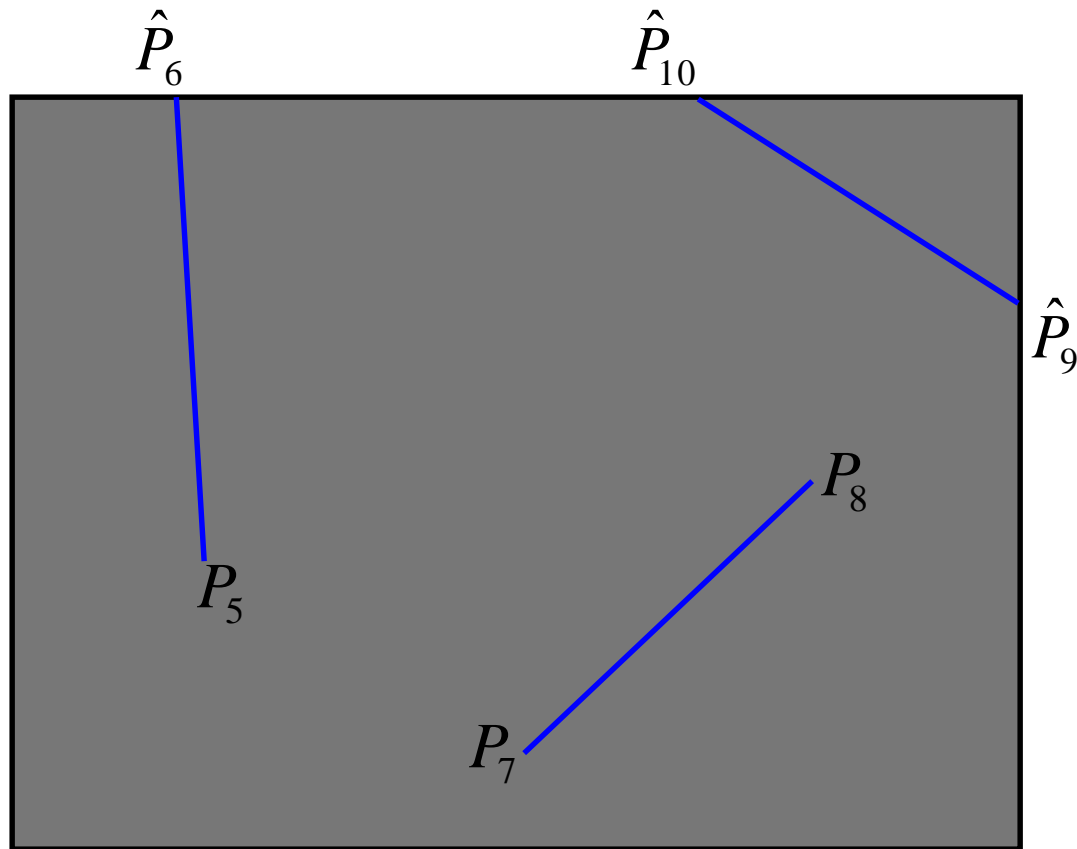
- ▶ Given a point (x, y) and clipping window (x_{min}, y_{min}) , (x_{max}, y_{max}) , determine if the point should be drawn



Review: Clipping Lines



Review: Clipping Lines



Review Clipping

▶ Simple line clipping algorithm

- compute intersection points
- clip the line segment between the outside point and intersection point

▶ Cohen-Sutherland

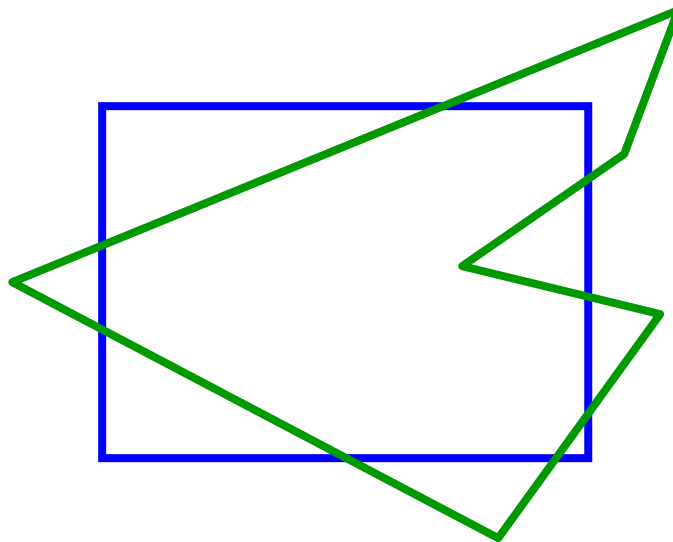
- region coding (9 regions, 4bits)
- best used when trivial acceptance and rejection is possible for most lines

▶ Liang-Barsky

- computation of t-intersections is cheap (only one division)
- computation of (x,y) clip points is only done once
- algorithm doesn't consider trivial accepts/rejects
- best when many lines must be clipped

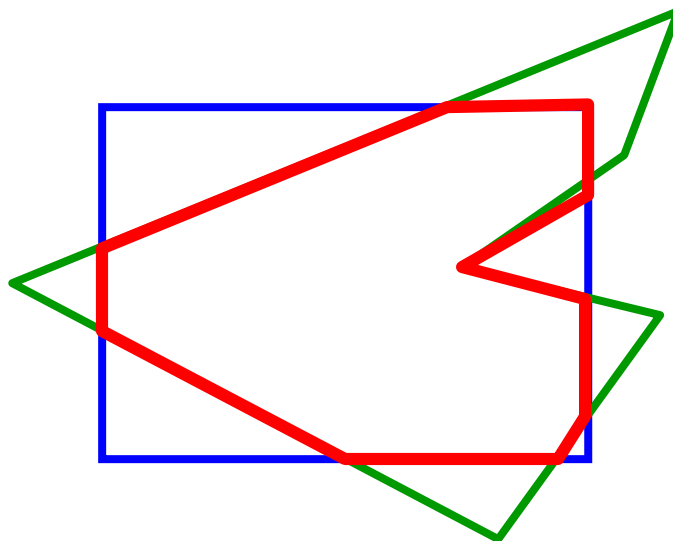
Clipping Polygons

- ▶ Clipping polygons is more complex than clipping the individual lines
 - ▶ - Input: polygon



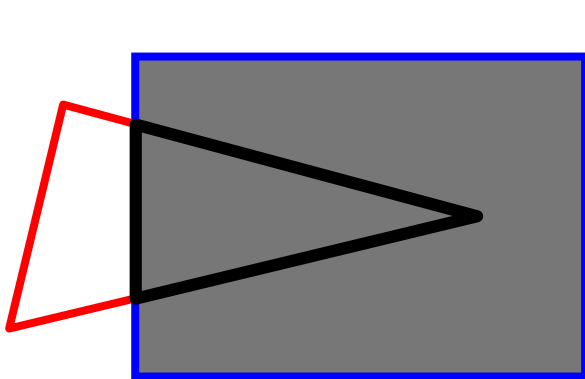
Clipping Polygons

- ▶ Clipping polygons is more complex than clipping the individual lines
 - ▶ - Input: polygon
 - ▶ - Output: original polygon, new polygon, or nothing

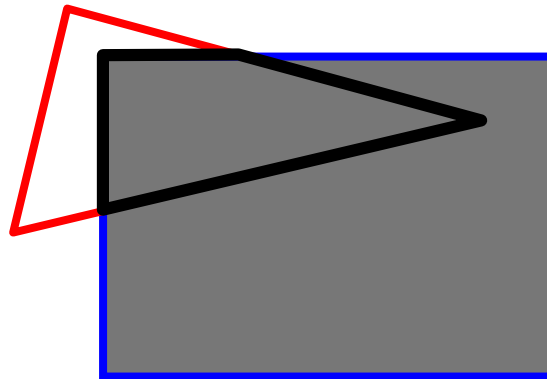


Why Is Polygon Clipping Hard?

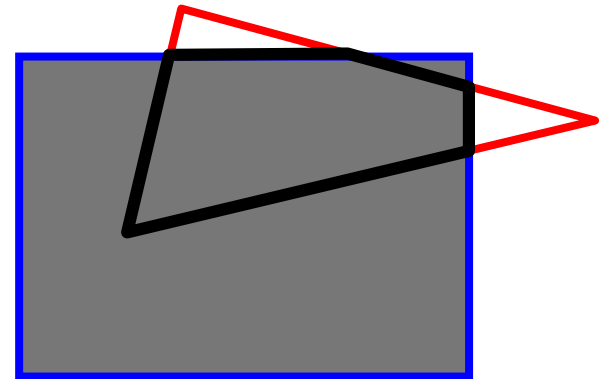
- ▶ What happens to a triangle during clipping?
 - possible outcomes:



triangle->triangle



triangle->quad



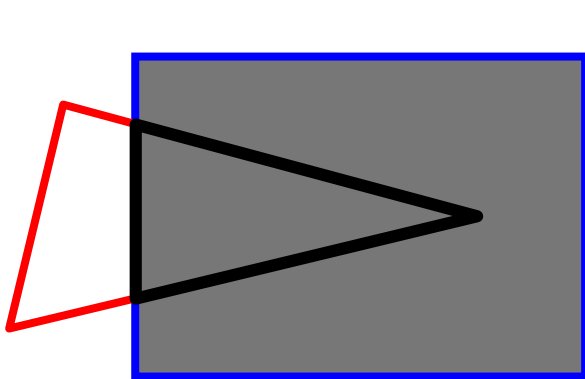
triangle->5-gon

Why Is Polygon Clipping Hard?

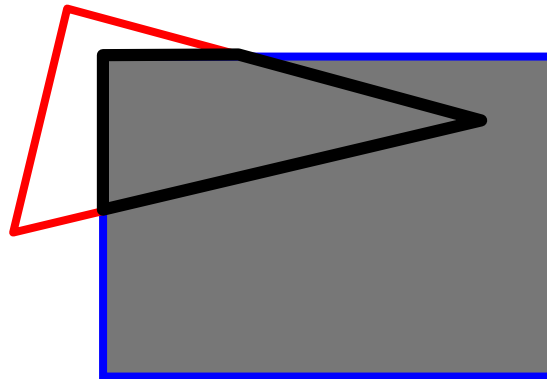
- ▶ What happens to a triangle during clipping?
 - possible outcomes: triangle, quad, or else?

Why Is Polygon Clipping Hard?

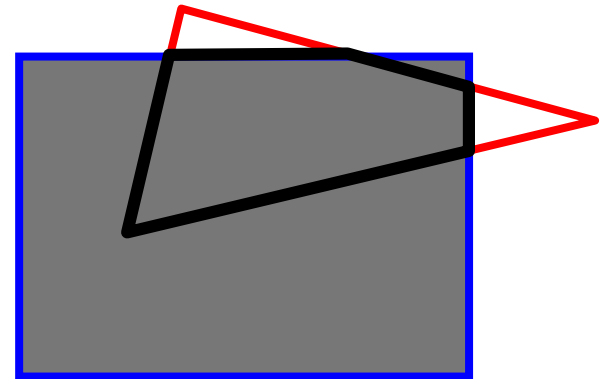
- ▶ What happens to a triangle during clipping?
 - possible outcomes:



triangle->triangle



triangle->quad

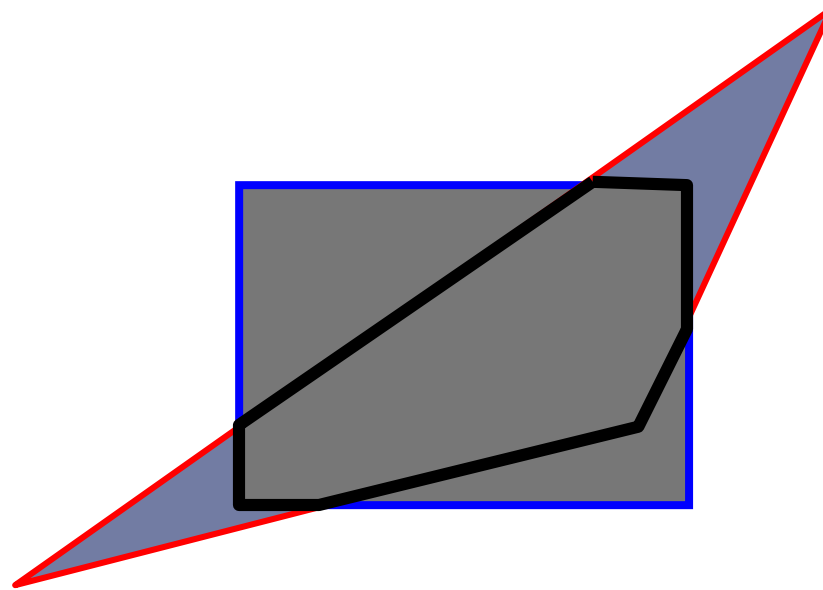


triangle->5-gon

How many sides a clipped triangle might have?

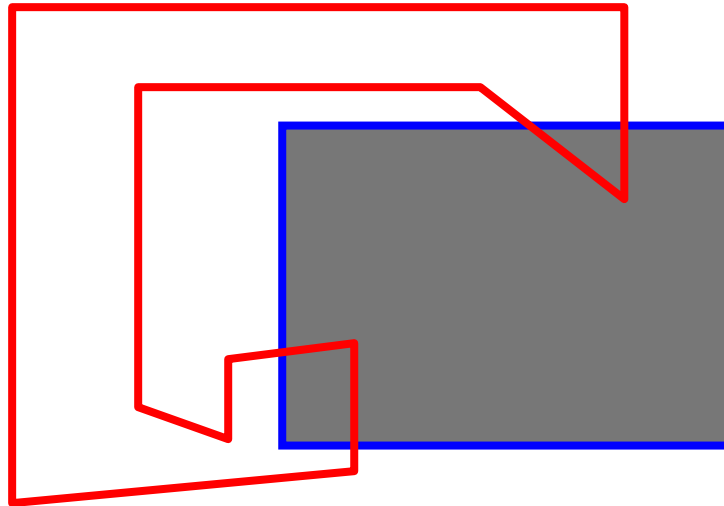
How Many Sides?

- ▶ Seven



Why Is Clipping Hard?

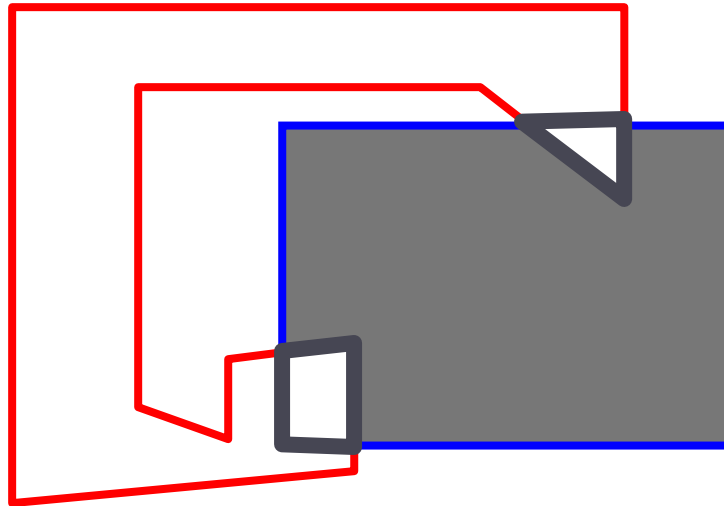
- ▶ A really tough case



Concave polygon -> Multiple polygons

Why Is Clipping Hard?

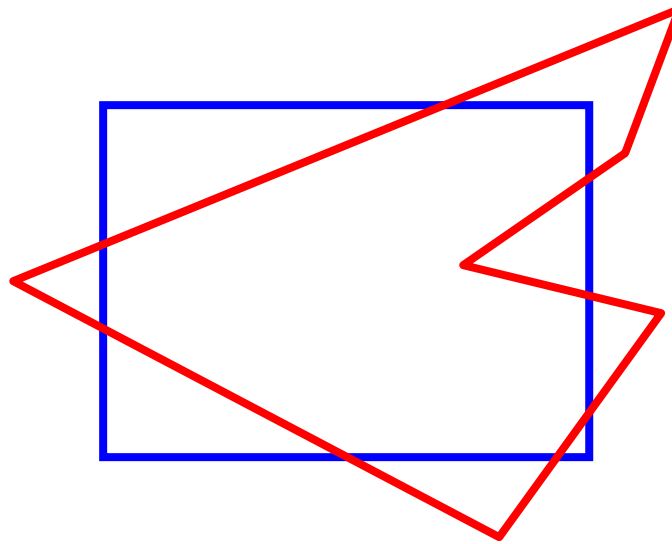
- ▶ A really tough case



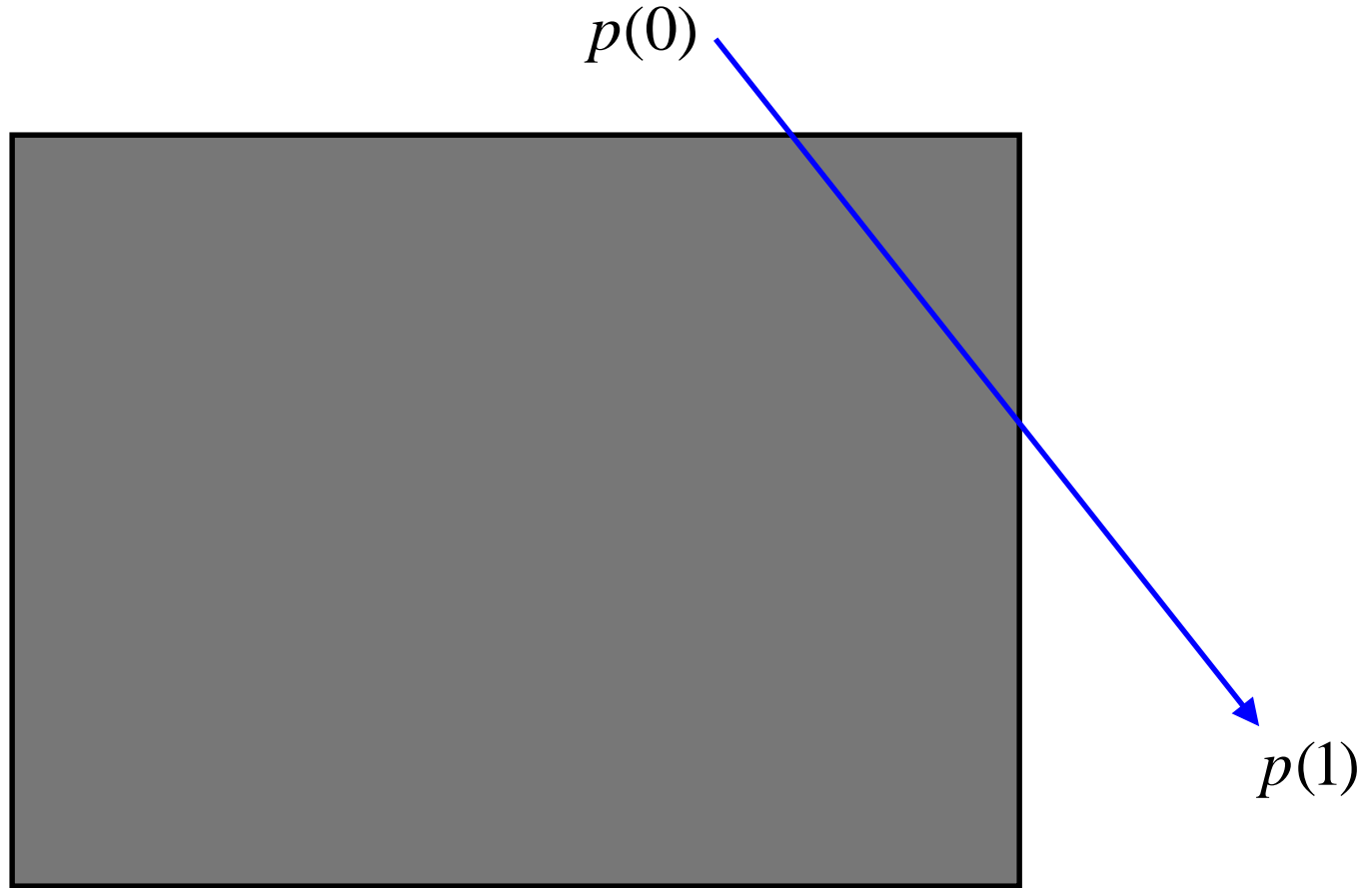
Outline

- ▶ Sutherland-Hodgman Clipping
 - convex polygons
- ▶ Weiler-Atherton Algorithm
 - general polygons

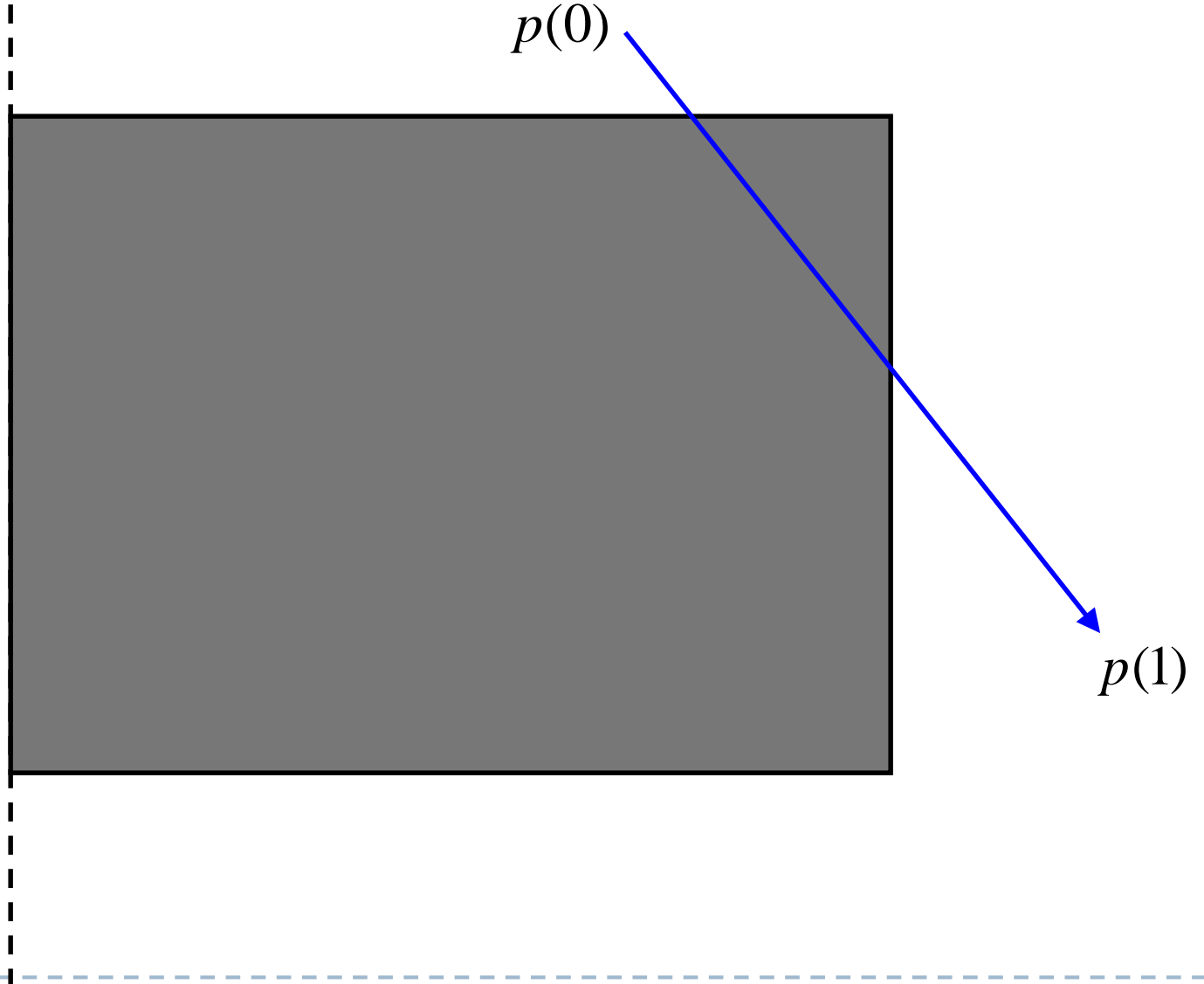
Any idea?



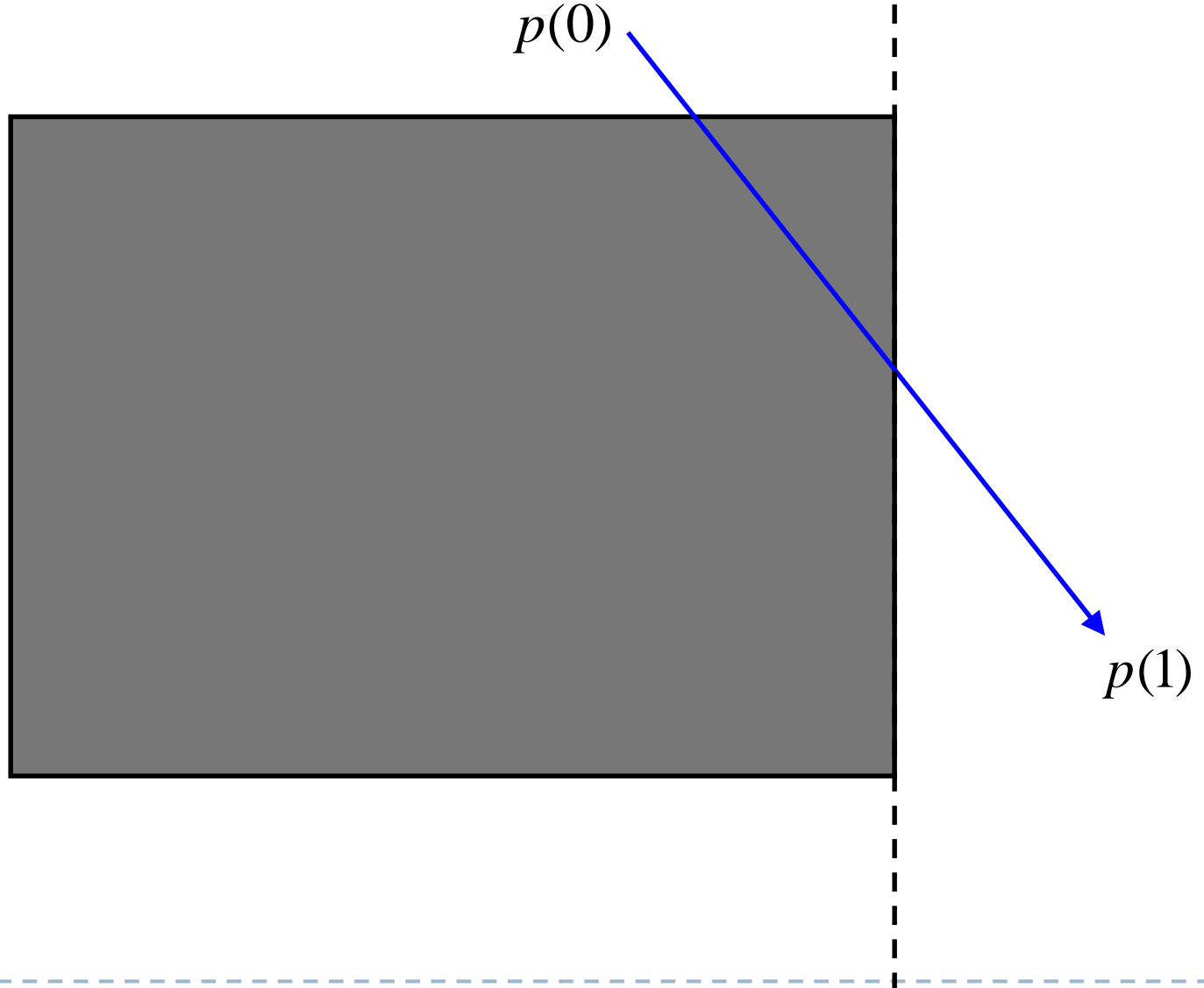
Review: Liang-Barsky Algorithm



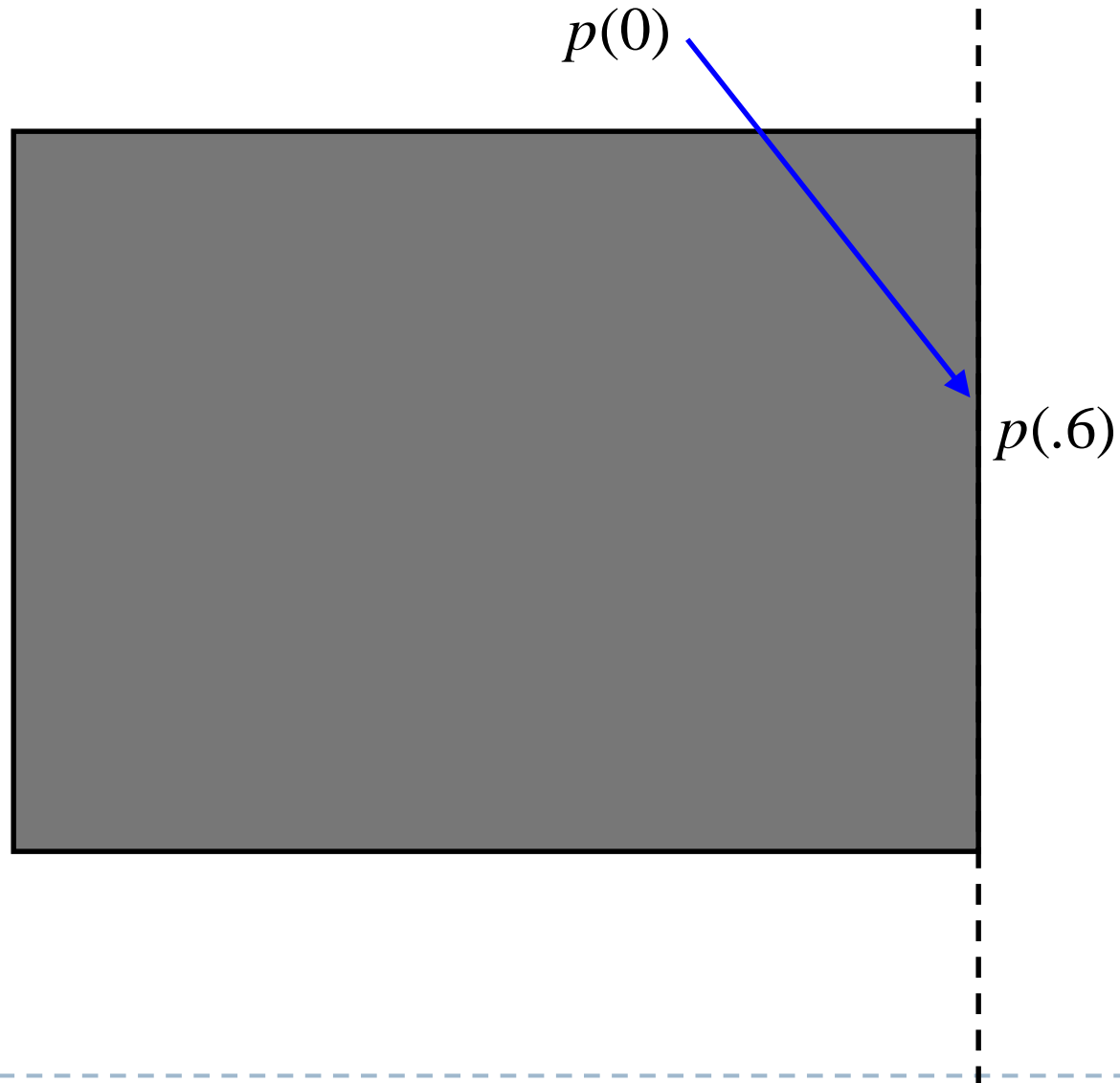
Review: Liang-Barsky Algorithm



Review: Liang-Barsky Algorithm

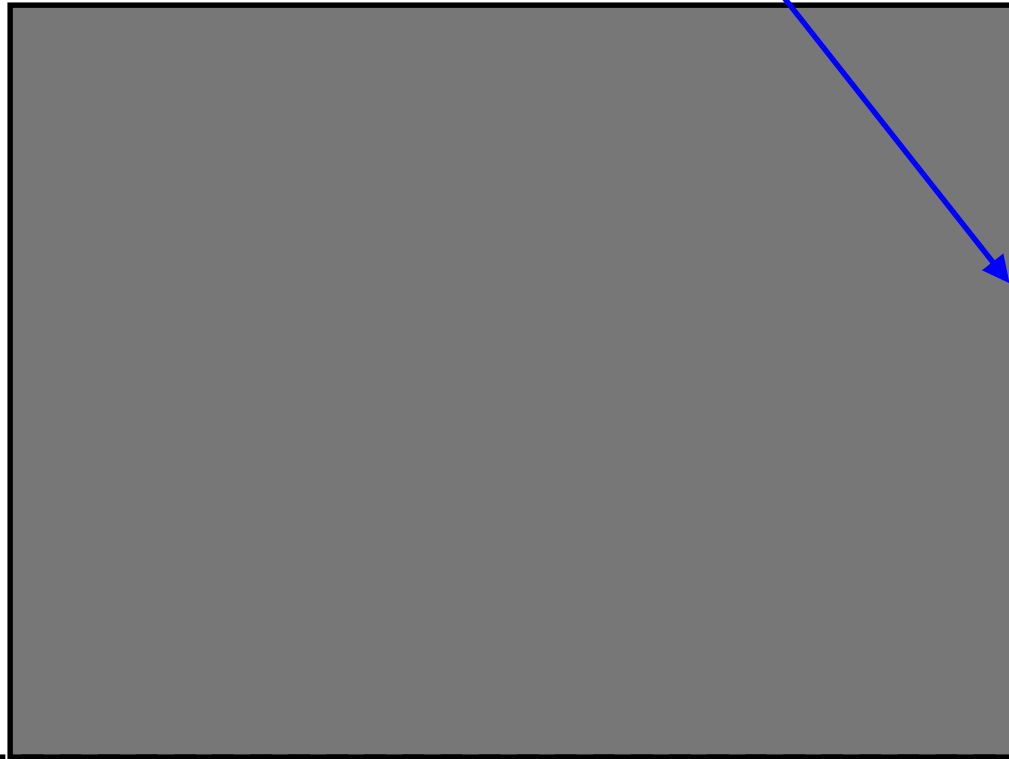


Liang-Barsky Algorithm



Review: Liang-Barsky Algorithm

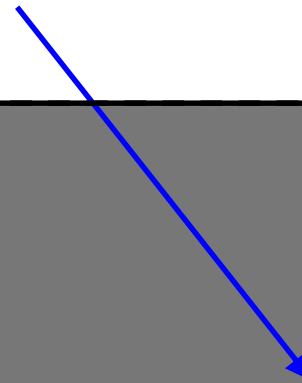
$p(0)$



$p(.6)$

Review: Liang-Barsky Algorithm

$p(0)$



$p(.6)$

Review: Liang-Barsky Algorithm

